Journal of Mathematical Research & Exposition, Vol.12, No.2, May. 1992

# Improvement of Sufficient Conditions for Stability of Discrete Scheme\*

Yang Qingmin (Hunan Computing Center, Changsha, china)

A.A. Samarsky has given some sufficient conditions for stability. For the norm  $\|\phi\|$ , the two layer scheme require  $B \ge \varepsilon E + o.5\tau A$ , the three layer scheme require  $B \ge \varepsilon E$ , where  $\varepsilon(>0)$  does not depend on  $\tau$  and h. In this paper for lower condition  $B > 0.5\tau A$ , B > 0, we still obtain the correspondent theorems . we use the definition and notation in [1].

### 1. Sufficient Conditions of Stability for Two Layer Scheme

Theorem 1.1 Assume the scheme

$$By_t + Ay = \phi \qquad , y(0) = y_0 \tag{1}$$

be original scheme variety. If

$$B > 0.5\tau A,\tag{2}$$

then scheme (1) is stable and the solution of problem (1) has priori estimation

$$||y(t+\tau)||_{\bar{A}} \le ||y_0||_{\bar{A}} + \frac{1}{\sqrt{2}} (\sum_{t'=0}^t \tau ||\phi(t')||^2)^{\frac{1}{2}},$$
 (3)

where  $\bar{A} = \varepsilon(\tau, h)A, \varepsilon(\tau, h) > 0$ .

**Theorom 1.2** Assume  $A = A^* > 0$  and

$$\sigma > \sigma_0, \sigma_0 = \frac{1}{2} - \frac{1}{\tau ||A||},\tag{4}$$

then scheme

$$y_t + A(\sigma \hat{Y} + (1 - \sigma)Y) = \phi, y(0) = y_0$$
 (5)

is stable and has priori estimation (3).

**Theorem 1.3** Assume  $A(t) = A^*(t) > 0$  and satisfy condition (4), them scheme (5) is stable and has estimation

$$||y(t+\tau)||_{\bar{A}} \leq ||y_0||_{\bar{A}} + \frac{1}{\sqrt{2}} \left( \sum_{t'=0}^{t} \tau ||A^{-1}(t')\phi(t')||^2 \right)^{\frac{1}{2}}, \tag{6}$$

$$||y(t+\tau)||_{\overline{A}} \leq ||y_0||_{\overline{A}} + \frac{1}{\sqrt{2}} \left( \sum_{t'=0}^t \tau ||\phi(t')||^2_{A^{-1}} \right)^{\frac{1}{2}}$$
 (7)

<sup>\*</sup>Received March 8, 1990.

where  $\bar{A} = \varepsilon(\tau, h, t)E, \bar{A} = \varepsilon(\tau, h, t)\delta(\tau, h, t)E, \varepsilon(\tau, h, t) > 0, \delta(\tau, h, t) > 0,$ 

Theorem 1.4 Assume

$$\begin{cases} A(t) = A^*(t) > 0, \text{ for all } t \in \bar{\omega}_{\tau}, \\ A(t) \text{ is Lipschitz continuous} \\ B(t) > 0, \text{ for all } t \in \bar{\omega}_{\tau} \end{cases}$$
(8)

and

$$B(t) > \varepsilon(\tau, h)E + o.5\tau A(t), \text{ for all } t \in \omega_{\tau}, \tag{9}$$

then the scheme (1) is stable and has priori estimation

$$||y(t+\tau)||_{\bar{A}(t)} \leq M_1(||y(0)||_{\bar{A}(0)} + \frac{1}{\sqrt{2}} (\sum_{t'=0}^t \tau ||\phi(t')||^2)^{\frac{1}{2}}, \tag{10}$$

where  $M_1 = e^{0.5c_3t_0}$ ,  $\bar{A}(t) = \varepsilon(\tau, h)A(t) \varepsilon(\tau, h) > 0$ .

Corollary 1.1 If the elements  $b_{ij}(t) - 0.5\tau a_{ij}(t)(i, j = 1, 2, ..., N)$  in  $B(t) - 0.5\tau A(t)$  are continuous or only have finite jump point of the first kind, then substituting condition  $B(t) > 0.5\tau A(t)$  for condition (9), the theorem 1.4 still holds.

## 2. Sufficient Conditions of Stability for Three Layer Scheme

Theorem 2.1 For scheme

$$By_{\hat{t}} + \tau^2 RY_{\bar{t}t} + AY = \phi, Y(\tau) = Y_1, Y(0) = Y_0, \tag{11}$$

assume  $A = A^* > 0, R = R^* > 0$ , them under conditions  $B > 0, R \ge \frac{1}{4}A$ , the scheme(11) is stable and its solution has priori estimation

$$||Y(t+\tau)|| \le ||y(\tau)|| + \frac{1}{\sqrt{2}} (\sum_{t'=\tau}^t \tau ||\phi(t')||^2)^{\frac{1}{2}},$$
 (12)

where  $||Y(t+\tau)|| = \frac{1}{4}(\bar{A}(Y(t)+Y(t+\tau)), y(t)+y(t+\tau)) + \tau^2((\bar{R}-\frac{1}{4}\bar{A})y_t(t), y_t(t)), \bar{R} = \varepsilon(\tau,h)R, \bar{A} = \varepsilon(\tau,h)A, \varepsilon(\tau,h,) > 0.$ 

**Theorem 2.2** Assume  $A(t) = A^*(t) > 0$ ,  $R(t) = R^*(t) > 0$ ,  $B(t) \ge \bar{\varepsilon}(\tau, h)E, A(t), R(t) - \frac{1}{4}A(t)$  are Lipschitz continuous and

$$R(t) \ge \frac{1}{4}A(t), \text{ for all } 0 < t = n\tau < t_0,$$
 (13)

then the scheme (11) is stable and has estimation

$$||Y(t+\tau)||_{(t)} \leq M_1 ||Y(\tau)||_{(0)} + M_2 \left(\sum_{t'=\tau}^t \tau ||\phi(t')||^2\right)^{\frac{1}{2}}, \tag{14}$$

where

$$Y(t+\tau)\|_{(t)} = \frac{1}{4}(\bar{A}(t)(y(t)+y(t+\tau)),y(t)+y(t+\tau)) + \tau^2((\bar{R}(t)-\frac{1}{4}\bar{A}(t))y_t(t),y_t(t)), (15)$$

 $M_1=e^{0.5c_3t_0}, M_2=rac{1}{\sqrt{2}}, c_3$  is a positive constant,  $\bar{\epsilon}(\tau,h)>0$ .

**Theorem 2.3** Assume  $A(t) = A^*(t) > 0$ ,  $R(t) = R^*(t) > 0$ ,  $B(t) \ge \bar{\varepsilon}(\tau, h)E$ , A(t), R(t) Lipschitz continuous and

$$R(t) \ge \frac{1+\varepsilon}{4} A(t), \text{ for all } 0 \le t = n\tau \le t_0, \tag{16}$$

where  $\varepsilon(>0)$  does not depend on  $\tau$  and h, then scheme (11) is stable and has estimation

$$||Y(t+\tau)||_{(t)} \leq M_1 ||Y(\tau)||_{(0)} + M_2 \left(\sum_{t'=\tau}^t \tau ||\phi(t')||^2\right)^{\frac{1}{2}}, \tag{17}$$

where  $\bar{\epsilon}(\tau, h) > 0$ ,  $M_1 = e^{0.5 \frac{2+\epsilon}{\epsilon} c_3 t_0}$ ,  $M_2 = \frac{1}{\sqrt{2}}$ .

Corollary 2.1 If the elements  $b_{ij}(t)(i, j = 1, 2..., N)$  in B(t) are continuous or only have finite jump point of the first kind. then substituting condition B(t) > 0 for condition  $B(t) \ge \bar{\varepsilon}(\tau, h)E$ , Theorem 2.2, 2.3 still hold.

#### REFERENCE

[1] A.A.Samarsky, Introduction to the Analysis of Difference Schenes, Moscow: Nauka, 1971 (In Russian).

# 离散格式稳定的充分条件的改进

杨 情 民 (湖南计算中心,长沙)

#### 摘 要

本文改进了 A. A. 萨多尔斯劳[1]中判稳的充分条件,把条件  $B \geqslant \epsilon E + 0.5 \tau A, B \geqslant \epsilon E$  放宽为:基本上只要求  $B > 0.5 \tau A, B > 0.$