

Systems of Matrix Equations over a Central Algebra *

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Abstract: Let Ω be a finite dimensional central algebra with an involutorial anti-automorphism and $\text{chart}\Omega \neq 2$. Two systems of matrix equations over Ω are considered. Necessary and sufficient conditions for the existences of general solutions, and per(skew)selfconjugate solutions of the systems are given, respectively.

Key words: central algebra; system of matrix equations; per(skew)selfconjugate matrix; regular matrix quadruple.

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1. Introduction

Throughout this paper, we denote a finite dimensional central algebra with an involution σ [1, p.112, Definition 1] over a field F by Ω and $\text{chart}\Omega \neq 2$, the set of all $m \times n$ matrices over Ω by $\Omega^{m \times n}$, the set of all $n \times n$ invertible matrices over Ω by $GL_n(\Omega)$, the set of all $m \times n$ matrices over $\Omega[\lambda]$ by $\Omega^{m \times n}[\lambda]$, and an $i \times i$ identity matrix by I_i .

Let $A = (a_{ij}) \in \Omega^{m \times n}$, $A^* = (\sigma(a_{m-j+1, n-i+1})) \in \Omega^{n \times m}$. Then $A \in \Omega^{n \times n}$ is called per(skew)selfconjugate if $A = A^*(-A^*)$. The set of all per(skew)selfconjugate matrices is denoted by $C_n S_n$.

For matrices A, B over Ω , it is easy to verify that $(A^*)^* = A$, $(AB)^* = B^*A^*$. Define $(A^*)^{-1} = A^{-*}$ if A is invertible. Suppose $A, B \in \Omega^{n \times n}$, $C, D \in \Omega^{m \times m}$, then (A, B, C, D) is called a regular matrix quadruple if there exists $\lambda \in F$ such that $A + \lambda B, C + \lambda D$ are invertible.

Many problems in systems and control theory require the solution of Sylvester's matrix equation $AX - XB = C$ or its generalization $AX - YB = C$. W. E. Roth [2] gave necessary and sufficient conditions for the consistency of the two matrix equations. The matrix equation $AXB - CXD = E$ appears in the numerical solution of implicit ordinary differential equations [3].

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In this paper, the following systems of matrix equations over Ω

$$\begin{cases} A_1 X^* - X B_1 = C_1 \\ A_2 X^* - X B_2 = C_2 \end{cases}, \quad (1.1)$$

$$\begin{cases} A_1 X B_1 - C_1 X D_1 = E_1 \\ A_2 X B_2 - C_2 X D_2 = E_2 \end{cases}, \quad (2.2)$$

are considered. Necessary and sufficient conditions are given for the existences of general solutions to (1.1), and a per(skew)selfconjugate solution to (1.2). As a particular case, auxiliary results dealing with the system of Sylvester equations over Ω are also presented.

2. Main results

To begin with the following

Theorem 2.1 Let $A \in \Omega^{m \times n}[\lambda]$, $B \in \Omega^{n \times m}[\lambda]$, $C \in \Omega^{m \times m}[\lambda]$. Then the matrix equation

$$AX^* - XB = C \quad (2.1)$$

has a solution X over Ω if and only if there exist $Q \in GL_{n+m}(\Omega)$ such that

$$\begin{bmatrix} -A & -C \\ O & B \end{bmatrix} = Q^* \begin{bmatrix} -A & O \\ O & B \end{bmatrix} Q. \quad (2.2)$$

Proof Suppose that

$$M_0 = \begin{bmatrix} A & O \\ O & B \end{bmatrix}, M_c = \begin{bmatrix} A & C \\ O & B \end{bmatrix}, J = \begin{bmatrix} -I_m & O \\ O & I_n \end{bmatrix}.$$

Let the matrix (2.1) have a solution X over Ω and

$$Q = \begin{bmatrix} I_n & X^* \\ O & I_m \end{bmatrix}, S = \begin{bmatrix} I_m & X \\ O & I_n \end{bmatrix}.$$

Then it is easy to verify that

$$M_0 Q = S M_c, Q^* J S = J. \quad (2.3)$$

Hence

$$Q^* J M_0 Q = J M_c, \quad (2.4)$$

i.e., (2.2) holds.

Conversely, let (2.2) hold, i.e., (2.4) hold, and $S = J^{-1} Q^{-*} J$. Then (2.3) holds. Suppose that

$$U = \begin{bmatrix} U_1 & U_{12} \\ U_{21} & U_2 \end{bmatrix} \begin{matrix} n \\ m \end{matrix} \in \Omega^{(m+n) \times (m+n)}, V = \begin{bmatrix} V_1 & V_{12} \\ V_{21} & V_2 \end{bmatrix} \begin{matrix} m \\ n \end{matrix} \in \Omega^{(m+n) \times (m+n)}, \quad (2.5)$$

then

$$U^* = \begin{bmatrix} U_2^* & U_{12}^* \\ U_{21}^* & U_1^* \end{bmatrix} \begin{matrix} m \\ n \end{matrix} \in \Omega^{(m+n) \times (m+n)}, V^* = \begin{bmatrix} V_2^* & V_{12}^* \\ V_{21}^* & V_1^* \end{bmatrix} \begin{matrix} n \\ m \end{matrix} \in \Omega^{(m+n) \times (m+n)}.$$

Let

$$T_c = \{(U, V) | M_0 U = V M_c, J U^* J M_0 = M_c J^* V^* J^*\}. \quad (2.6)$$

Then for $(U, V) \in T_c$, we have the following

$$\begin{cases} AU_1 - V_1 A = 0 \\ BU_{21} - V_{21} A = 0 \\ AU_{12} - V_1 C - V_{12} B = 0 \\ BU_2 - V_{21} C - V_2 B = 0 \\ AV_2^* - U_2^* A = C V_{21}^* \\ AV_{12}^* - U_{12}^* B = C V_1^* \\ U_{21}^* A - B V_{21}^* = 0 \\ U_1^* B - B V_1^* = 0 \end{cases}. \quad (2.7)$$

It is easy to verify that T_c is a finite dimensional linear space over F with scalar multiplication and addition defined as follows:

$$(U, V)b = (Ub, Vb), b \in F, (U_1, V_1) + (U_2, V_2) = (U_1 + U_2, V_1 + V_2).$$

For $C = 0$, let T_0 be defined by (2.6). According to (2.3), it is not difficult to verify that

$$(U, V) \in T_c \Leftrightarrow (UQ^{-1}, VS^{-1}) \in T_0.$$

So,

$$\dim T_c = \dim T_0. \quad (2.8)$$

Define a linear map $f : \Omega^{(m+n) \times (m+n)} \times \Omega^{(m+n) \times (m+n)} \rightarrow \Omega^{(m+n) \times m}$ by the following

$$f(U, V) = \begin{bmatrix} V_1 \\ V_{21} \end{bmatrix}.$$

It is obvious that in the case $C = 0$ we have $(U, V) = (I_{m+n}, I_{m+n}) \in T_0$ and therefore

$$\begin{bmatrix} I_m \\ 0 \end{bmatrix} \in f(T_0). \quad (2.9)$$

Let $f_c = f|_{T_c}$, $f_0 = f|_{T_0}$. Then it follows from (2.7) that

$$\ker f_c = \ker f_0. \quad (2.10)$$

Suppose U and V are as in (2.5) and

$$K = \begin{bmatrix} U_1 & 0 \\ U_{21} & 0 \end{bmatrix}, L = \begin{bmatrix} V_1 & 0 \\ V_{21} & 0 \end{bmatrix},$$

then it follows from (2.7) that if $(U, V) \in T_c$, then $(K, L) \in T_0$. Hence we have

$$\text{Im}f_c \subseteq \text{Im}f_0. \quad (2.11)$$

It follows from (2.8), (2.10) and

$$\dim \ker f_c + \dim \text{Im}f_c = \dim T_c, \quad \dim \ker f_0 + \dim \text{Im}f_0 = \dim T_0$$

that $\dim \text{Im}f_c = \dim \text{Im}f_0$. Therefor (2.11) yields $\text{Im}f_c = \text{Im}f_0$, i.e. $f(T_c) = f(T_0)$. By (2.9), $\begin{bmatrix} I_m \\ 0 \end{bmatrix} \in f(T_c)$. Consequently there exists $(U, V) \in T_c$ such that $V_1 = I_m$. In view of (2.7), we have

$$AU_{12} - V_{12}B = C, \quad (2.12)$$

$$AV_{12}^* - U_{12}^*B = C. \quad (2.13)$$

Let

$$X = \frac{1}{2}(V_{12} + U_{12}^*). \quad (2.14)$$

Then X is a solution over Ω of the matrix equation (2.1).

Corollary 2.2 Let $A \in \Omega^{m \times n}, B \in \Omega^{n \times m}, C \in \Omega^{m \times m}$. Then the matrix equation (2.1) is consistent if and only if there exist $Q \in \text{GL}_{n+m}(\Omega)$ such that (2.2) holds.

Theorem 2.3 Let $A, B, C \in \Omega^{m \times m}[\lambda]$. Then the Sylvester matrix equation

$$AX - XB = C \quad (2.15)$$

has a solution $X \in \mathbf{C}_m$ if and only if there exists $Q \in \text{GL}_{2m}(\Omega)$ such that

$$\begin{bmatrix} A & C \\ O & B \end{bmatrix} = Q^{-1} \begin{bmatrix} A & O \\ O & B \end{bmatrix} Q, Q^* \begin{bmatrix} -I_m & O \\ O & I_m \end{bmatrix} Q = \begin{bmatrix} -I_m & O \\ O & I_m \end{bmatrix}.$$

Proof In the proof of Theorem 2.1, let $m = n, V = U, S = Q$ and replace (2.14) by $X = \frac{1}{2}(U_{12} + U_{12}^*)$. Then we can complete the proof by adjusting slightly the rest of the proof of Theorem 2.1.

Theorem 2.4 Let $A, B, C \in \Omega^{m \times m}[\lambda]$. Then the Sylvester matrix equation (2.15) has a solution $X \in \mathbf{S}_m$ if and only if there exists $Q \in \text{GL}_{2m}(\Omega)$ such that

$$\begin{bmatrix} A & C \\ O & B \end{bmatrix} = Q^{-1} \begin{bmatrix} A & O \\ O & B \end{bmatrix} Q, Q^* Q = I_{2m}.$$

Proof In the proof of theorem 2.1, let

$$T_c = \{(U, V) | M_0 U = U M_c, U^* M_0 = M_c U^*\}.$$

Then for (2.7),(2.12),(2.13) and (2.14) become respectively the following

$$\begin{cases} AU_1 - U_1A = 0 \\ BU_{21} - U_{21}A = 0 \\ AU_{12} - U_1C - U_{12}B = 0 \\ BU_2 - U_{21}C - U_2B = 0 \\ AU_2^* - U_2^*A + CU_{21}^* = 0 \\ AU_{12}^* - U_{12}^*B + CU_1^* = 0 \\ U_{21}^*A - BU_{21}^* = 0 \\ U_1^*B - BU_1^* = 0 \end{cases},$$

$$AU_{12} - U_{12}B = C, \quad A(-U_{12}^*) - (-U_{12}^*B) = C, \quad X = \frac{1}{2}(U_{12} - U_{12}^*).$$

By adjusting slightly the rest of the proof of Theorem 2.1, we can complete the proof. \square

Theorem 2.5 Let $A_i \in \Omega^{m \times n}, B_i \in \Omega^{n \times m}, C_i \in \Omega^{m \times m}, i = 1, 2$. Then the matrix equation (1.1) is consistent if and only if there exist $Q \in \text{GL}_{n+m}(\Omega)$ such that

$$Q^* \left[\begin{pmatrix} -A_1 & O \\ O & B_1 \end{pmatrix} - \lambda \begin{pmatrix} -A_2 & O \\ O & B_2 \end{pmatrix} \right] Q = \begin{pmatrix} -A_1 & -C_1 \\ O & B_1 \end{pmatrix} - \lambda \begin{pmatrix} -A_2 & -C_2 \\ O & B_2 \end{pmatrix}.$$

Proof The system (1.1) is equivalent to the following

$$(A_1 - \lambda A_2)X^* - X(B_1 - \lambda B_2) = C_1 - \lambda C_2.$$

By Theorem 2.1, we can complete immediately the proof. \square

Now we consider the system (1.2) where $A_i, C_i \in \Omega^{m \times m}, B_i, D_i \in \Omega^{n \times n}, E_i \in \Omega^{m \times n}$, and (A_i, C_i, B_i, D_i) is a regular matrix quadruple, $i = 1, 2$. There exists $\lambda_i \in F$ such that $C_i + \lambda_i A_i$ and $B_i + \lambda_i D_i$ are invertible, $i = 1, 2$. Let

$$\widetilde{A}_i = (C_i + \lambda_i A_i)^{-1} A_i, \widetilde{D}_i = D_i (B_i + \lambda_i D_i)^{-1}, \widetilde{E}_i = (C_i + \lambda_i A_i)^{-1} E_i (B_i + \lambda_i D_i)^{-1}. \quad (2.16)$$

It is clear that the system (1.2) is equivalent to the following

$$(\widetilde{A}_1 - \lambda \widetilde{A}_2)X - (\widetilde{D}_1 - \lambda \widetilde{D}_2) = \widetilde{E}_1 - \lambda \widetilde{E}_2.$$

Hence by Theorem 2.3 and Theorem 2.4 we have respectively the following theorems.

Theorem 2.6 Let $A_i, C_i, B_i, D_i, E_i \in \Omega^{n \times n}$, and (A_i, C_i, B_i, D_i) be a regular matrix quadruple, and $\widetilde{A}_i, \widetilde{D}_i, \widetilde{E}_i$ be defined as (2.16) $i = 1, 2$. Then the system (1.2) has a solution $X \in \mathbb{C}_n$ if and only if there exists $Q \in \text{GL}_{2n}(\Omega)$ such that

$$Q^* \begin{bmatrix} -I_n & O \\ O & I_n \end{bmatrix} Q = \begin{bmatrix} -I_n & O \\ O & I_n \end{bmatrix},$$

$$\begin{bmatrix} \widetilde{A}_1 & \widetilde{E}_1 \\ O & \widetilde{D}_1 \end{bmatrix} - \lambda \begin{bmatrix} \widetilde{A}_2 & \widetilde{E}_2 \\ O & \widetilde{D}_2 \end{bmatrix} = Q^{-1} \left[\begin{bmatrix} \widetilde{A}_1 & O \\ O & \widetilde{D}_1 \end{bmatrix} - \lambda \begin{bmatrix} \widetilde{A}_2 & O \\ O & \widetilde{D}_2 \end{bmatrix} \right] Q.$$

Theorem 2.7 Let $A_i, C_i, B_i, D_i, E_i \in \Omega^{n \times n}$, and (A_i, C_i, B_i, D_i) be a regular matrix quadruple, and $\widetilde{A}_i, \widetilde{D}_i, \widetilde{E}_i$ be defined as (2.16), $i = 1, 2$. Then the system (1.2) has a solution $X \in S_n$ if and only if there exists $Q \in GL_{2n}(\Omega)$ such that

$$\begin{bmatrix} \widetilde{A}_1 & \widetilde{E}_1 \\ O & \widetilde{D}_1 \end{bmatrix} - \lambda \begin{bmatrix} \widetilde{A}_2 & \widetilde{E}_2 \\ O & \widetilde{D}_2 \end{bmatrix} = Q^{-1} \left[\begin{pmatrix} \widetilde{A}_1 & O \\ O & \widetilde{D}_1 \end{pmatrix} - \lambda \begin{pmatrix} \widetilde{A}_2 & O \\ O & \widetilde{D}_2 \end{pmatrix} \right] Q, Q^* Q = I_{2n}.$$

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中心代数上的矩阵方程组

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摘 要: 设 Ω 是一个特征非 2 的具有对合反自同构的有限维中心代数. 本文研究 Ω 上的两个矩阵方程组, 分别给出了其有一般解和次(斜)自共轭解的充要条件.