C^{∞} Compactness for Minimal Submanifolds in the Unit Sphere *

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Abstract: In this paper we study the C^{∞} compactness for minimal submanifolds in the unit sphere. We obtain two compactness theorems. As an application, we prove that there is a positive number δ (n), such that if the square of the length of the second fundamental form of a minimal submanifold in the unit sphere is less than $\frac{2}{3}n + \delta(n)$, it must be totally geodesic or diffeomorphic to a Veronese surface.

Key words: minimal submanifold; totally geodesic; compactness theorem.

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1. Introduction

The compactness theorem give us good understanding of the behavior of Riemannian manifolds under certain restricts of curvature, volume and diameter, see for example [2,6,7,11,8]. In [12], Shen obtained a $C^{1,\alpha}$ convergence theorem for Riemannian submanifolds. However, $C^{1,\alpha}$ convergence is not enough for many applications. In this paper, we will study C^{∞} convergence for minimal submanifolds which are isometrically immersed or imbedded in the unit sphere. We should mention that Choi and Schoen^[4] have obtained the C^{∞} compactness theorem for minimal surfaces in three dimensional manifolds.

Suppose M^n is a minimal n-dimensional submanifold of the (n+p)-dimensional unit sphere S^{n+p} . First let's fix some notations. We denoted by V(M), d(M), s(M), Ric(M) and K(M) the volume, diameter, square of the length of the second fundamental form, Ricci curvature, and sectional curvature of M^n respectively. Let $\Gamma_{n+p} = \{M^n | M^n \text{ is a minimal closed Riemannian submanifold immersed in <math>S^{n+p}\}$. Here, we don't distinguish isometric manifolds. Given a sequence of Riemannian manifolds $\{M_i^n\}_{i=1}^{\infty}$, we say $\{M_i^n\}_{C^{\infty}}^{\infty}$ converges to a Riemannian manifold M^n , if for all but finitely many i, there exist diffeomorphisms $f_i: M^n \to M_i^n$ such that $\{f_i^*g_i\}_{C^k}$ converges to g for every g, where g_i and g are the Riemannian metrics of M_i^n and M respectively. Now we can express our

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theorems as follows:

Theorem 1 Let $\Gamma_{n+1}^s = \{M^n \in \Gamma_{n+1} | M^n \text{ be imedded in } S^{n+1}, s(M) \leq s\}$. Then Γ_{n+1}^s contains only finitely many diffeomorphism types of n-manifolds. Moreover, Γ_{n+1}^s is C^{∞} compact.

One may hope to prove that $\{M^n \in \Gamma_{n+1} | s(M) \leq s\}$ is C^{∞} compact. However, this is not ture, because s(M) can not control V(M) if M^n is only immersed. For higher codimensional case, we have

Theorem 2 Let $\Gamma_{n+p}^{V,s} = \{M^n \in \Gamma_{n+p} | V(M) \leq V, s(M) \leq s\}$. Then $\Gamma_{n+p}^{V,s}$ contains only finitely many diffeomorphism types of n-manifolds. Moreover, $\Gamma_{n+p}^{V,s}$ is C^{∞} compact.

As an interesting application of the above theorem, we have the following pinching theorem, which improves the previous pinching constant is [3,5,14].

Theorem 3 For every $n \geq 2$, there is a positive number $\delta(n)$, such that if $s(M) \leq \frac{2}{3}n + \delta(n)$, $M^n \in \Gamma_{n+p}$, then M^n must be totally geodesic or diffeomorphic to the Veronese surface.

2. Some necessary estimates

To prove the above theorems, we need to estimate the bounds of curvature, volume and diameter of a minimal submanifold. Some facts are well known.

Lemma 1 If $M^n \in \Gamma_{n+p}$, then $V(M) \geq V(S^n)$. Where $V(S^n)$ is the volume of the standard n-dimensional sphere.

Proof This follows from [9].

Lemma 2 If $M^n \in \Gamma_{n+1}^s$, then $V(M) \leq C(s)$, where C(s) is a constant depend only on s.

Proof This follows from [10].

To estimate curvature and their derivatives, we shall introduce the structure equations of submanifold. Suppose $M^n \in \Gamma_{n+p}$. Choose local orthonormal frame $\{e_1, e_2, \cdots, e_{n+p}\}$ for S^{n+p} , such that when restricted to M^n , $\{e_1, e_2, \cdots, e_n\}$ is tangent to M^n . The dual 1-forms are denoted by $\{\omega_1, \omega_2, \cdots, \omega_{n+p}\}$. We have the structure equations for S^{n+p} as follows:

$$egin{aligned} d\omega_A &= -\sum_{B=1}^{n+p} \omega_{AB} \wedge \omega_B, A \in \{1,2,\cdots,n+p\}, \omega_{AB} = -\omega_{BA}, \ d\omega_{AB} &= -\sum_{i=1}^{n+p} \omega_{AC} \wedge \omega_{CB} + \Omega_{AB}, \ A,B \in \{1,2,\cdots,n+p\}, \end{aligned}$$

where $\Omega_{AB} = \frac{1}{2} \sum_{C,D=1}^{n+p} R_{ABCD} \omega_C \wedge \omega_D$, $R_{ABCD} = \delta_{AC} \delta_{BD} - \delta_{AD} \delta_{BC}$.

When restricted to M^n , the above equations turn out to be

$$d\omega_{i} = -\sum_{j=1}^{n} \omega_{ij} \wedge \omega_{j}, i \in \{1, 2, \dots, n\}, \omega_{ij} = -\omega_{ji},$$

$$d\omega_{ij} = -\sum_{k=1}^{n} \omega_{ik} \wedge \omega_{kj} + \Omega_{ij}, i, j \in \{1, 2, \dots, n\},$$

$$\Omega_{ij} = \frac{1}{2} \sum_{k,l=1}^{n} K_{ijkl} \omega_{k} \wedge \omega_{l}, K_{ijkl} = R_{ijkl} = \sum_{\alpha} (h_{ik}^{\alpha} h_{jl}^{\alpha} - h_{il}^{\alpha} h_{jk}^{\alpha}),$$

$$(1)$$

where h_{ij}^{α} satisfies

$$egin{aligned} \omega_{lpha i} &= \sum_{j=1}^n h_{ij}^lpha \omega_j, h_{ij}^lpha &= h_{ji}^lpha, \ d\omega_{lphaeta} &= -\sum_{\gamma=n+1}^{n+p} \omega_{lpha\gamma} \wedge \omega_{\gammaeta} + \Omega_{lphaeta}, \ \Omega_{lphaeta} &= rac{1}{2} \sum_{kl} K_{lphaeta kl} \omega_k \wedge \omega_l, K_{lphaeta kl} &= R_{lphaeta kl} + \sum_i (h_{ik}^lpha h_{il}^eta - h_{il}^lpha h_{jk}^eta). \end{aligned}$$

The second fundamental form of M^n is

$$H = \sum_{lpha ij} h^{lpha}_{ij} \omega_i \otimes \omega_j \otimes e_{lpha}.$$

Then s(M), the square of the length of H, is equal to $\sum_{\alpha ij} (h_{ij}^{\alpha})^2$.

Lemma 3 For $M^n \in \Gamma_{n+p}$, we have

$$|K(M)| \le 1 + 2s(M), \operatorname{Ric}(M) \ge (n-1)[1 - s(M)/n].$$

Proof The first estimate follows from (1). Next we will verify the second estimate at every fixed point $x \in M^n$. Denoted by H^{α} the $n \times n$ matrix whose (i,j) entry is h_{ij}^{α} . Set $G = \sum_{\alpha} (H^{\alpha})^2$. By choosing suitable frame $\{e_1, e_2, \dots, e_n\}$ we can assume that G is diagonal at x. Thus by the minimality of M^n and (1), we have

$$\sum_{j} K_{ijkj} = (n-1)\delta_{ik} - G_{ik}. \tag{2}$$

Also, we have

$$n(h_{ij}^{\alpha})^{2} = (n-1)(h_{ij}^{\alpha})^{2} + (-\sum_{j \neq i} h_{jj}^{\alpha})^{2}$$

$$\leq (n-1)(h_{ii}^{\alpha})^{2} + (n-1)\sum_{j \neq i} (h_{jj}^{\alpha})^{2} = (n-1)\sum_{j} (h_{jj}^{\alpha})^{2}.$$
(3)

Then by (2) and (3), we know that $\sum_{i} K_{ijkj} = 0$ for $i \neq k$, and

$$egin{aligned} \sum_{j} K_{ijij} &= (n-1) - \sum_{lpha j} (h_{ij}^{lpha})^2 = (n-1) - \sum_{lpha} [(h_{ii}^{lpha})^2 + \sum_{j
eq i} (h_{ij}^{lpha})^2] \ &\geq (n-1) - \sum_{lpha} rac{n-1}{n} \sum_{ij} (h_{ij}^{lpha})^2 = (n-1)[1 - s(M)/n]. \end{aligned}$$

Lemma 4 If $M^n \in \Gamma_{n+p}^{V,s}$, then $d(n,p,s) \leq d(M) \leq D(n,p,s,V)$.

Proof The lower bound follows from Lemma 1,3 and the Bishop-Gromov volume comparison theorem. The upper bound follows from Lemma 3 and a simple packing argument.

Lemma 5 If $M^n \in \Gamma^{V,s}_{n+p}$, then

$$\left|D^kRm\right|\leq C_k(n,p,s,V), k\geq 1.$$

Where Rm is the curvature tensor of M^n , D^kRm is the k-th covariant derivative of Rm, $|\cdot|$ is the pointwise norm, $C_k(n, p, s, V) = C_k$ is a constant depend only on n, p, s and V.

To prove this lemma, we only need to estimate $|D_m H|$, the pointwise norm of m-th covariant derivative of the second fundamental form. We put

$$D^m H = \sum_{lpha i_1 i_2 \cdots i_{m+2}} h^{lpha}_{i_1 i_2 \cdots i_{m+2}} \omega i_1 \otimes \omega_{i_2} \cdots \otimes \omega i_{i_{m+2}} \otimes e_{lpha},$$
 $|D^m H|^2 = \sum_{lpha i_1 i_2 \cdots i_{m+2}} (h^{lpha}_{i_1 i_2 \cdots i_{m+2}})^2.$

We have the following Ricci identity

$$h_{i_{1}\dots i_{s}kl}^{\alpha} - h_{i_{1}\dots i_{s}lk}^{\alpha} = \sum_{r} \sum_{i=1}^{s} h_{i_{1}\dots i_{j-1}ri_{j+1}\dots i_{s}}^{\alpha} R_{ri_{j}kl} + \sum_{\beta} h_{i_{1}\dots i_{s}}^{\beta} R_{\beta\alpha kl}. \tag{4}$$

The computation of [3] gives

$$\sum_{k} h_{ijkk}^{\alpha} = \sum_{nk} h_{nk}^{\alpha} R_{nijk} + \sum_{nk} R_{nkjk} + \sum_{\beta k} h_{ik}^{\beta} R_{\beta \alpha jk}.$$
 (5)

More generally, we have

$$\sum_{k} h_{i_{1}i_{2}\cdots i_{m}kk}^{\alpha} = \sum_{k} \left(h_{i_{1}i_{2}\cdots i_{m-1}i_{m}k}^{\alpha} - h_{i_{1}i_{2}\cdots i_{m-1}ki_{m}}^{\alpha} \right)_{k} +$$

$$\sum_{k} \left(h_{i_{1}i_{2}\cdots ki_{m}k}^{\alpha} - h_{i_{1}i_{2}\cdots kki_{m}}^{\alpha} \right) + \left(\sum_{k} h_{i_{1}i_{2}\cdots i_{m-1}kk}^{\alpha} \right)_{i_{m}}, m \geq 3.$$
 (6)

Now we have

$$\frac{1}{2}\nabla |D^m H|^2 = -\left|D^{m+1}H\right|^2 - \sum_{\alpha i_1 i_2 \cdots i_{m+2}} h^{\alpha}_{i_1 i_2 \cdots i_{m+2}} \sum_k h^{\alpha}_{i_1 i_2 \cdots i_{m+2} kk}.$$
 (7)

- 194 -

Where ∇ is the Laplacian $-\operatorname{tr} D^2$.

Proof of Lemma 5 By definition, $|D^0H|^2 = s(M) \le s$. Integrate (7) on M^n , using Stokes' formula and (6), we get $\int_{M^n} |DH|^2 \le d_1$.

Now suppose

$$\left|D^kH\right|\leq C_k, k=0,1,2,\cdots,m-1,m\geq 1.$$

$$\int_{M^n}\left|D^mH\right|^2\leq d_m.$$

From (4), (5), (6), and (7), we have

$$\frac{1}{2}\nabla |D^m H|^2 \le - \left|D^{m+1} H\right|^2 + \alpha |D^m H|^2 + b |D^m H|.$$

Integrating gives

$$\int_{M^n} \left| D^{m+1} H \right|^2 \le d_{m+1}.$$

Now, from (8), we can deduce

$$|D^{m}H| \nabla |D^{m}H| \leq |d|D^{m}H||^{2} - |D^{m+1}H|^{2} + a|D^{m}H|^{2} + b|D^{m}H|$$

$$\leq a|D^{m}H|^{2} + b|D^{m}H|.$$
(8)

We have applied Kato's inequality $|d|D^mH|^2 \leq |D^{m+1}H|^2$. Rewrite (9) as

$$\nabla(|D^mH|+b/a) \le a(|D^mH|+b/a).$$

Then by Theorem 3 of Appendix five of [1], we get the estimate $|D^m H| + b/a \le C_m$. We should mention that Lemma 3, Lemma 4, Theorem 2 of Appendix one of [1], and Theorem 3 of Appendix four of [1] provide the condition needed by the theorem we used.

By induction we get the estimate $|D^k H| \leq C_k$ for all $k \geq 0$. Now by the structure equations, we also get the estimate of $|D^k Rm|$, which finishes the proof.

3. Proofs of the theorems

We are now in a position to prove Theorem 1, 2, and 3.

Proof of Theorem 1 and 2 First let's consider $\Gamma^{V,s}_{n+p}$. By lemma 1, 4 and 5 and the C^k version of the Cheeger-Gromov compactness theorem (cf. [6,8,11]), we know that $\Gamma^{V,s}_{n+p}$ consists of only finitely many diffeomorphism types of n-manifolds. Moreover, given a sequence of $\{M^n_i\}$ which belong to $\Gamma^{V,s}_{n+p}$, we can choose a subsequence which C^{∞} converges to a n-manifold M^n . Without loss of generality, we can assume that $\{M^n_i\}$ itself C^{∞} converges to M^n . Thus for i sufficiently large, there are diffeomorphisms $f_i:M^n\to M^n_i$, such that $f_i^*g_iC^{\infty}$ converges to a Riemannian metric g on M^n . Where $g_i=\varphi^*_i(ds^2)$ is induced by the isometric immersion $\varphi_i:M^n_i\to S^{n+p}\subset R^{n+p+1},ds^2$ is the standard metric on R^{n+p+1} . We shall prove that $M^n\in\Gamma^{V,s}_{n+p}$ which will finish the proof of Theorem 2.

1

By Takahashi's theorem [13], $\nabla_{gi}\varphi_i = n\varphi_i$. Then by similar calculations of Lemma 5, we can find constants C_k which independ of i, such that $\left|D_{g_i}^k\varphi_i\right| \leq C_k$. Thus

$$\left|D_{f_i^*g_i}^k(\varphi_if_i)\right| = \left|D_{g_i}^k\varphi_i\right| \leq C_k.$$

Now since $\{f_i^*g_i\}C^{\infty}$ converges to g, for i sufficiently large, we have

$$\left|D_g^k(\varphi_i f_i)\right| \leq 2C_k.$$

Then by Arzela-Ascoli's theorem, there is subsequence of $\{\varphi_i f_i\}$ which C^{∞} converges to a C^{∞} map $\varphi: M^n \to R^{n+p+1}$. It's apparent that $\varphi^*(ds^2) = g, \nabla_g \varphi = n\varphi$. Thus again by Takahashi's theorem [13], φ is a minimal isometric immersion which maps M^n into S^{n+p} . Now it's easy to see that $M^n \in \Gamma_{n+p}^{V,s}$.

Next let's consider Γ^s_{n+1} . By Lemma 2 and the above proof, we know that Γ^s_{n+1} consists of finitely many diffeomorphism type of n-manifolds. Moreover, given a sequence of $\{M^n_i\} \in \Gamma^s_{n+1}$, we can find a subsequence C^{∞} converges to M^n which is minimally immersed in S^{n+1} . We want to prove that $M^n \in \Gamma^s_{n+1}$. We will assume that it's $\{M^n_i\}$ itself that C^{∞} convergest to M^n . By the above proof, we assume that there are diffeomorphisms $f_i: M^n \to M^n_i$ and isometric imbeddings $\varphi_i: M^n_i \to S^{n+1} \subset R^{n+2}$. It's only need to prove that φ is an imbedding.

Suppose on the contrary, φ is not imbedded. Then there are different points $x, y \in M^n$ such that $\varphi(x) = \varphi(y) = p \in S^{n+1}$. Since φ is an immersion, there are geodesic balls $B_x(\varepsilon)$, $B_y(\varepsilon)$ such that $\varphi|B_x(2\varepsilon)$ and $\varphi|B_y(2\varepsilon)$ are imbeddings, $B_x(2\varepsilon) \cap B_y(2\varepsilon) = \varphi$. Note that these balls are selected with respect to the metric φ^*g_0 , where g_0 is the standard metric on S^{n+1} . Now there is a positive real number δ such that

$$\operatorname{dist}_{g_0}(\varphi(\partial B_x(\varepsilon)),p)>\delta, \operatorname{dist}_{g_0}(\varphi(\partial B_y(\varepsilon)),p)>\delta.$$

Where dist_{g0} is the distance function on S^{n+1} . Since $\{\varphi_i f_i\}C^{\infty}$ converges to φ , for sufficiently large i, we have

$$\mathrm{dist}_{g_0}(\varphi_i f_i(\partial B_x(\varepsilon)), p) > \frac{\delta}{2}, \ \ \mathrm{dist}_{g_0}(\varphi_i f_i(\partial B_y(\varepsilon)), p) > \frac{\delta}{2}.$$

Put $x_i = \varphi_i f_i(x), y_i = \varphi_i f_i(y)$. Then $\lim_{i \to \infty} x_i = \lim_{i \to \infty} y_i = p$. So for sufficiently large i, we have

$$\mathrm{dist}_{g_0}(\boldsymbol{x_i},p)<\min(\frac{\delta}{10},\frac{\mathrm{arccot}\sqrt{s}}{4}),\ \mathrm{dist}_{g_0}(y_i,p)<\min(\frac{\delta}{10},\frac{\mathrm{arccot}\sqrt{s}}{4}).$$

Now for every i, choose $z_i \in \varphi_i f_i(\overline{B_u(\varepsilon)})$, such that

$$\operatorname{dist}_{g_0}(x_i, \varphi_i f_i(\overline{B_y(\varepsilon)}) = \operatorname{dist}_{g_0}(x_i, z_i).$$

Then the following inequalities hold for i sufficiently large

$$egin{aligned} \operatorname{dist}_{g_0}(p,z_i) & \leq \operatorname{dist}_{g_0}(p,y_i) + \operatorname{dist}_{g_0}(y_i,x_i) + \operatorname{dist}_{g_0}(x_i,z_i) \ & \leq \operatorname{dist}_{g_0}(p,y_i) + 2 \operatorname{dist}_{g_0}(y_i,x_i) \leq 3 \operatorname{dist}_{g_0}(p,y_i) + 2 \operatorname{dist}_{g_0}(p,x_i) < rac{\delta}{2}. \end{aligned}$$

This implies that $z_i \in \varphi_i f_i(B_y(\varepsilon))$. Choose a minimal geodesic γ_i in S^{n+1} which connects z_i and x_i . Then by the formula for the first variation of arclength, we know that $\dot{\gamma}_i(0) \in N(\varphi_i f_i(M^n))$, where $N(\varphi_i f_i(M^n))$ is the normal bundle of $\varphi_i f_i(M^n)$. Set $l_i = \operatorname{dist}_{q_0}(z_i, x_i)$. Then

 $\exp_{z_i}^{\perp}(l_i\dot{\gamma}_i(0)) = \exp_{x_i}^{\perp}(0),$

where \exp^{\perp} is the normal exponential map of $\varphi_i f_i(M^n)$. Now $l_i \leq \operatorname{dist}_{g_0}(y_i, x_i) < \frac{1}{2}\operatorname{arccot}\sqrt{s}$, which implies that \exp^{\perp} is not injective on $\{v \in N(\varphi_i f_i(M^n))| \|v\|_{g_0} < \operatorname{arccot}\sqrt{s}\}$. But this contradicts with Lemma 3 of [10], so our proof is completed. \square Finally, we prove Theorem 3, which gives an application of the above results.

Proof of Theorem 3 Recall the theorems in [5] that, given $M^n \in \Gamma_{n+p}$, if $s(M) \leq \frac{2}{3}n$, then M^n must be totally geodesic or is the Veronese surface (in which case n=2, s=4/3). Suppose on the contrary the conclusion of Theorem 3 is not ture. Then there is $M_i^n \in \Gamma_{n+p}$ such that $s(M_i) \leq \frac{2}{3}n + \varepsilon_i$, $\lim_{i \to \infty} \varepsilon_i = 0$, M_i^n is neither totally geodesic nor diffeomorphic to the Veronese surface. We can assume that $0 < \varepsilon_i < \frac{n}{12}$. By lemma 3 we know that $Ric(M) \geq \frac{1}{4}(n-1)$. By the Bishop-Gromov volume comparison theorem, we have $V(M_i) \leq V(S^n(2))$, where $S^n(2)$ is the sphere in R^{n+1} with radius 2. So $M_i^n \in \Gamma_{n+p}^{V,s}$. Where $V = V(S^n(2))$, $S = \frac{3}{4}n$. Applying Theorem 2 we get a $M^n \in \Gamma_{n+p}^{V,s}$, such that a subsequence of $\{M_i^n\}C^\infty$ converges to M^n . Now it's easy to see that $s(M) \leq \frac{2}{3}n$. By the definition of C^∞ convergence and the above assumption, M^n is not the Veronese surface. So by the pinching theorem mentioned at the beginning, M^n must be totally geodesic. So s(M) = 0. But this implies that for isufficiently large, $s(M_i) < \frac{2}{3}n$, which yields that M_i is totally geodesic. This is a contradiction. \square

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单位球面中极小子流形的 C^{∞} 紧性

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摘 要: 本文研究了单位球面中极小子流形的 C^{∞} 紧性,并得到两个紧性定理,作为应用,我们证明了存在正数 $\delta(n)$,如果单位球面中极小子流形的第 2 基本形式的长度平方小于 $\frac{2}{3}n + \delta(n)$,则它必须是全测地的或微分同胚于 Veronese 曲面.

关键词: 极小子流形; 全测地线; 紧性定理.