

Multiple Positive Solutions to a Nonlinear Two-point Boundary Value Problem with p -Laplacian

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Abstract: By a simple application of a new three functionals fixed point theorem, sufficient conditions are obtained to guarantee the existence of at least three positive solutions for p -Laplacian equation: $(\varphi_p(u'))' + a(t)f(t, u(t)) = 0$ subject to nonlinear boundary value conditions. An example is presented to illustrate the theory.

Key words: boundary value problem; p -Laplacian operator; positive solution; the three functionals fixed point theorem.

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1. Introduction

This paper deals with the p -Laplacian equation

$$(\varphi_p(u'))' + a(t)f(t, u(t)) = 0, \quad t \in (0, 1) \quad (1)$$

subject to the following nonlinear boundary conditions

$$u(0) - B_0(u'(0)) = 0, \quad u(1) + B_1(u'(1)) = 0 \quad (2)$$

where $\varphi_p(x) = |x|^{p-2}x, p > 1$.

In [1], using the three functionals fixed point theorem due to Avery and Henderson^[4], HE Xiao-ming and GE Wei-gao obtained at least two positive solutions of (1)(2) when $f(t, u) = f(u)$; In [2], the authors yielded at least triple positive solutions to BVP (1)(2) by applying the five functionals fixed point theorem on cone; In [3], by Leggett-Williams fixed point theorem, the authors obtained three positive solutions of three-point BVPs when $p = 2$. But the conditions for the methods and techniques mentioned above are difficult to check. This paper will apply a new three functionals three fixed points theorem proved in literature^[5] to study the existence of three positive solutions of BVP(1)(2). Our results are new and different from those in [1–3] and very easy to check.

The following conditions are satisfied throughout this paper.

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(H₁) $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$ is continuous;

(H₂) $B_0(v)$ and $B_1(v)$ are both nondecreasing continuous odd functions defined on $(-\infty, +\infty)$, and satisfy that there are nonnegative numbers l and L such that

$$lv \leq B_i(v) \leq Lv, \quad v \geq 0, \quad i = 0, 1;$$

(H₃) $a(t)$ is a nonnegative measurable function defined on $(0,1)$, and $a(t)$ is not identical zero on any compact subinterval of $(0,1)$. Furthermore, $a(t)$ satisfies

$$0 < \int_0^1 a(t)dt < +\infty.$$

2. Some definitions and lemmas

In this section, we provide some background definitions cited from cone theory in Banach spaces.

Definition 2.1 Let $(E, \|\cdot\|)$ be a real Banach space. A nonempty, closed, convex set $P \subset E$ is said to be a cone provided the following are satisfied:

- (i) If $y \in P$ and $\lambda \geq 0$, then $\lambda y \in P$;
- (ii) If $y \in P$ and $-y \in P$, then $y = 0$.

If $P \subset E$ is a cone, we denote the order induced by P on E by \leq , that is, $x \leq y$ if and only if $y - x \in P$.

Definition 2.2 Given a cone P in a real Banach space E , a functional $\psi : P \rightarrow \mathbb{R}$ is said to be increasing on P , provided $\psi(x) \leq \psi(y)$ for all $x, y \in P$ with $x \leq y$.

Definition 2.3 Given a nonnegative continuous functional γ on a cone P of E , we define for each $d > 0$ the set

$$P(\gamma, d) = \{x \in P : \gamma(x) < d\}.$$

The following fixed point theorem is fundamental and important to the proofs of our main results.

Lemma 2.1^[5] Let P be a cone in a Banach space E . Let α, β and γ be three increasing, nonnegative and continuous functionals on P , satisfying for some $c > 0$ and $M > 0$ such that

$$\gamma(x) \leq \beta(x) \leq \alpha(x), \quad \|x\| \leq M\gamma(x)$$

for all $x \in \overline{P(\gamma, c)}$. Suppose there exists a completely continuous operator $T : \overline{P(\gamma, c)} \rightarrow P$ and $0 < a < b < c$ such that

- (i) $\gamma(Tx) < c$, for all $x \in \partial P(\gamma, c)$;
- (ii) $\beta(Tx) > b$, for all $x \in \partial P(\beta, b)$;

(iii) $P(\alpha, a) \neq \emptyset$, and $\alpha(Tx) < a$, for all $x \in \partial P(\alpha, a)$.

Then T has at least three fixed points $x_1, x_2, x_3 \in \overline{P(\gamma, c)}$ such that

$$0 \leq \alpha(x_1) < a < \alpha(x_2), \quad \beta(x_2) < b < \beta(x_3), \quad \gamma(x_3) < c.$$

3. Main results

Let the Banach space $E = C([0, 1])$ be endowed the norm $\|x\| = \max_{t \in [0, 1]} |x(t)|$. And choose the cone $P \subset E$ defined by

$$P = \{x \in E : x(t) \text{ is nonnegative concave on } [0, 1]\}.$$

It follows from (H_2) that there exists $\delta \in (0, \frac{1}{2})$ such that

$$0 < \int_{\delta}^{1-\delta} a(t) dt < +\infty \quad (3)$$

and hence the function

$$y(x) := \varphi_q\left(\int_{\delta}^x a(t) dt\right) + \varphi_q\left(\int_x^{1-\delta} a(t) dt\right), \quad \delta \leq x \leq 1 - \delta$$

is continuous and positive on $[\delta, 1 - \delta]$, where $\varphi_q(x) := |x|^{1/(p-1)} \operatorname{sgn} x$.

We define the following nonnegative, increasing and continuous functionals

$$\gamma(u) = \frac{1}{2}(u(\delta) + u(1 - \delta)),$$

$$\beta(u) = \max_{\delta \leq t \leq 1-\delta} u(t),$$

$$\alpha(u) = \max_{0 \leq t \leq 1} u(t).$$

Obviously, for every $u \in P$, we have $\gamma(u) \leq \beta(u) \leq \alpha(u)$.

Lemma 3.1^[1] Let $u \in P$ and $\delta \in (0, 1/2)$, then $u(t) \geq \delta\|u\|$, for all $t \in [\delta, 1 - \delta]$.

From Lemma 3.1 and the definition of $\gamma(u)$, one has $\gamma(u) \geq \delta\|u\|$. Thus

$$\|u\| \leq \frac{1}{\delta} \gamma(u), \quad \text{for all } u \in P.$$

We shall use the following notations:

$$K = \min_{\delta \leq x \leq 1-\delta} y(x),$$

$$\eta = \max\{(L + 1 - \delta)\varphi_q\left(\int_0^{\delta} a(r) dr\right), (L + 1 - \delta)\varphi_q\left(\int_{1-\delta}^1 a(r) dr\right)\},$$

$$\xi = \min \left\{ \begin{array}{l} l\varphi_q\left(\int_{\delta}^1 a(r) dr\right) + \delta\varphi_q\left(\int_{\delta}^{1-\delta} a(r) dr\right), \\ l\varphi_q\left(\int_0^{1-\delta} a(r) dr\right) + \delta\varphi_q\left(\int_{\delta}^{1-\delta} a(r) dr\right), \\ \frac{l[\varphi_q\left(\int_0^{\delta} a(r) dr\right) + \varphi_q\left(\int_{1-\delta}^1 a(r) dr\right)] + K\delta}{2} \end{array} \right\},$$

$$\lambda = (L + 1 - \delta)\varphi_q\left(\int_0^1 a(r)dr\right).$$

Now we give the main result of this paper.

Theorem 3.1 Assume that (H_1) – (H_3) hold, and that there exist positive constants $0 < a < b < \frac{\xi a}{\eta} < \delta^2 c$ such that

$$(H_4) \quad f(t, \omega) < \varphi_p\left(\frac{c}{\lambda}\right), \text{ if } \delta \leq t \leq 1 - \delta, \delta c \leq \omega \leq \frac{c}{\delta};$$

$$(H_5) \quad f(t, \omega) > \varphi_p\left(\frac{b}{\xi}\right), \text{ if } 0 \leq t \leq 1, 0 \leq \omega \leq \frac{b}{\delta};$$

$$(H_6) \quad f(t, \omega) < \varphi_p\left(\frac{a}{\eta}\right), \text{ if } 0 \leq t \leq 1, 0 \leq \omega \leq a.$$

Then, the BVP (1)+(2) has at least three positive solutions u_1, u_2 and u_3 such that

$$0 \leq \alpha(u_1) < a < \alpha(u_2), \quad \beta(u_2) < b < \beta(u_3), \gamma(u_3) < c.$$

Proof We define an operator $T : P(\gamma, c) \rightarrow E$ by

$$(Tu)(t) = \begin{cases} B_0 \circ \varphi_q\left(\int_0^\sigma a(r)f(r, u(r))dr\right) + \int_0^t \varphi_q\left(\int_s^\sigma a(r)f(r, u(r))dr\right)ds, & 0 \leq t \leq \sigma \\ B_1 \circ \varphi_q\left(\int_\sigma^1 a(r)f(r, u(r))dr\right) + \int_t^1 \varphi_q\left(\int_\sigma^s a(r)f(r, u(r))dr\right)ds, & \sigma \leq t \leq 1 \end{cases}$$

for each $u \in P$, where $\sigma = 0$ if $(Tu)'(0) = 0$; $\sigma = 1$ if $(Tu)'(1) = 0$; otherwise, σ is a solution of the equation

$$z_0(x) = z_1(x),$$

where

$$z_0(x) = B_0 \circ \varphi_q\left(\int_0^x a(r)f(r, u(r))dr\right) + \int_0^x \varphi_q\left(\int_s^x a(r)f(r, u(r))dr\right)ds, \quad 0 \leq x < 1,$$

$$z_1(x) = B_1 \circ \varphi_q\left(\int_x^1 a(r)f(r, u(r))dr\right) + \int_x^1 \varphi_q\left(\int_x^s a(r)f(r, u(r))dr\right)ds, \quad 0 < x \leq 1.$$

It is shown in [6] that σ exists and the operator $T : P(\gamma, c) \rightarrow E$ is well defined. In particular, if $u \in \overline{P(\gamma, c)}$, we also have $Tu \in P$. So $T : \overline{P(\gamma, c)} \rightarrow P$.

It is easy to prove that $T : \overline{P(\gamma, c)} \rightarrow P$ is completely continuous.

We now show that all the conditions of Lemma 2.1 are satisfied. To make use of property (i) of Lemma 2.1, we choose $u \in \partial P(\gamma, c)$, then $\gamma(u) = \frac{1}{2}(u(\delta) + u(1 - \delta)) = c$. If we recall that $\|u\| \leq \frac{1}{\delta}\gamma(u)$, we have

$$\delta c \leq \delta\|u\| \leq u(t) \leq \frac{c}{\delta}, \quad \delta \leq t \leq 1 - \delta.$$

Then assumption (H_4) implies

$$f(s, \omega(s)) < \varphi_p\left(\frac{c}{\lambda}\right), \quad \delta \leq s \leq 1 - \delta.$$

Therefore,

$$\begin{aligned} \gamma(Tu) &= \frac{1}{2}(Tu(\delta) + Tu(1 - \delta)) \leq Tu(\delta) \\ &= B_1 \circ \varphi_q\left(\int_\sigma^1 a(r)f(r, u(r))dr\right) + \int_\delta^1 \varphi_q\left(\int_\sigma^s a(r)f(r, u(r))dr\right)ds \\ &\leq L\varphi_q\left(\int_0^1 a(r)f(r, u(r))dr\right) + \int_\delta^1 \varphi_q\left(\int_0^1 a(r)f(r, u(r))dr\right)ds \end{aligned}$$

$$\begin{aligned}
&= (L+1-\delta)\varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right) \\
&< (L+1-\delta)\varphi_q\left(\int_0^1 a(r)dr\right) \cdot \frac{c}{\lambda} \\
&= c, \quad \text{if } \sigma < \delta,
\end{aligned}$$

$$\begin{aligned}
\gamma(Tu) &= \frac{1}{2}(Tu(\delta) + Tu(1-\delta)) \leq Tu(1-\delta) \\
&= B_0 \circ \varphi_q\left(\int_0^\sigma a(r)f(r,u(r))dr\right) + \int_0^{1-\delta} \varphi_q\left(\int_s^\sigma a(r)f(r,u(r))dr\right)ds \\
&\leq L\varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right) + \int_0^{1-\delta} \varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right)ds \\
&= (L+1-\delta)\varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right) \\
&< (L+1-\delta)\varphi_q\left(\int_0^1 a(r)dr\right) \cdot \frac{c}{\lambda} \\
&= c, \quad \text{if } \sigma > 1-\delta,
\end{aligned}$$

$$\begin{aligned}
2\gamma(Tu) &= (Tu(\delta) + Tu(1-\delta)) \\
&= B_0 \circ \varphi_q\left(\int_0^\sigma a(r)f(r,u(r))dr\right) + \int_0^\delta \varphi_q\left(\int_s^\sigma a(r)f(r,u(r))dr\right)ds + \\
&\quad B_1 \circ \varphi_q\left(\int_\sigma^1 a(r)f(r,u(r))dr\right) + \int_{1-\delta}^1 \varphi_q\left(\int_\sigma^s a(r)f(r,u(r))dr\right)ds \\
&\leq L\varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right) + \int_0^\delta \varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right)ds + \\
&\quad L\varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right) + \int_{1-\delta}^1 \varphi_q\left(\int_0^1 a(r)f(r,u(r))dr\right)ds \\
&< (2L+2\delta)\varphi_q\left(\int_0^1 a(r)dr\right) \cdot \frac{c}{\lambda} \\
&< (2L+2-2\delta)\varphi_q\left(\int_0^1 a(r)dr\right) \cdot \frac{c}{\lambda} \\
&= 2c, \quad \text{if } \delta \leq \sigma \leq 1-\delta.
\end{aligned}$$

Hence, condition (i) is satisfied.

Secondly, we show that (ii) of Lemma 2.1 is fulfilled. For this, we select $u \in \partial P(\beta, b)$. Then $\beta(u) = \max_{\delta \leq t \leq 1-\delta} u(t) = b$. Noticing that $\|u\| \leq \frac{1}{\delta}\gamma(u) \leq \frac{1}{\delta}\beta(u) = \frac{b}{\delta}$, we have

$$0 \leq u(t) \leq \frac{b}{\delta}, \quad 0 \leq t \leq 1.$$

By (H_5) , we have

$$f(s, \omega(s)) > \varphi_p\left(\frac{b}{\xi}\right), \quad 0 \leq s \leq 1$$

and so

$$\begin{aligned}
 \beta(Tu) &= \max_{\delta \leq t \leq 1-\delta} Tu(t) \geq Tu(1-\delta) \\
 &= B_1 \circ \varphi_q \left(\int_{\sigma}^1 a(r)f(r, u(r))dr \right) + \int_{1-\delta}^1 \varphi_q \left(\int_{\sigma}^s a(r)f(r, u(r))dr \right) ds \\
 &\geq l\varphi_q \left(\int_{\delta}^1 a(r)f(r, u(r))dr \right) + \int_{1-\delta}^1 \varphi_q \left(\int_{\delta}^{1-\delta} a(r)f(r, u(r))dr \right) ds \\
 &> [l\varphi_q \left(\int_{\delta}^1 a(r)dr \right) + \delta\varphi_q \left(\int_{\delta}^{1-\delta} a(r)dr \right)] \cdot \frac{b}{\xi} \\
 &\geq \xi \cdot \frac{b}{\xi} \\
 &= b, \quad \text{if } \sigma < \delta,
 \end{aligned}$$

$$\begin{aligned}
 \beta(Tu) &= \max_{\delta \leq t \leq 1-\delta} Tu(t) \geq Tu(\delta) \\
 &= B_0 \circ \varphi_q \left(\int_0^{\sigma} a(r)f(r, u(r))dr \right) + \int_0^{\delta} \varphi_q \left(\int_s^{\sigma} a(r)f(r, u(r))dr \right) ds \\
 &\geq l\varphi_q \left(\int_0^{1-\delta} a(r)f(r, u(r))dr \right) + \int_0^{\delta} \varphi_q \left(\int_{\delta}^{1-\delta} a(r)f(r, u(r))dr \right) ds \\
 &> [l\varphi_q \left(\int_0^{1-\delta} a(r)dr \right) + \delta\varphi_q \left(\int_{\delta}^{1-\delta} a(r)dr \right)] \cdot \frac{b}{\xi} \\
 &\geq \xi \cdot \frac{b}{\xi} \\
 &= b, \quad \text{if } \sigma > 1-\delta,
 \end{aligned}$$

$$\begin{aligned}
 2\beta(Tu) &= 2 \max_{\delta \leq t \leq 1-\delta} Tu(t) \geq Tu(\delta) + Tu(1-\delta) \\
 &= B_0 \circ \varphi_q \left(\int_0^{\sigma} a(r)f(r, u(r))dr \right) + \int_0^{\delta} \varphi_q \left(\int_s^{\sigma} a(r)f(r, u(r))dr \right) ds \\
 &\quad + B_1 \circ \varphi_q \left(\int_{\sigma}^1 a(r)f(r, u(r))dr \right) + \int_{1-\delta}^1 \varphi_q \left(\int_{\sigma}^s a(r)f(r, u(r))dr \right) ds + \\
 &\geq l\varphi_q \left(\int_0^{\delta} a(r)f(r, u(r))dr \right) + \int_0^{\delta} \varphi_q \left(\int_{\delta}^{\sigma} a(r)f(r, u(r))dr \right) ds + \\
 &\quad + l\varphi_q \left(\int_{1-\delta}^1 a(r)f(r, u(r))dr \right) + \int_{1-\delta}^1 \varphi_q \left(\int_{\sigma}^{1-\delta} a(r)f(r, u(r))dr \right) ds \\
 &> \{ [l\varphi_q \left(\int_0^{\delta} a(r)dr \right) + \varphi_q \left(\int_{1-\delta}^1 a(r)dr \right)] + \delta [\varphi_q \left(\int_{\delta}^{\sigma} a(r)dr \right) + \varphi_q \left(\int_{\sigma}^{1-\delta} a(r)dr \right)] \} \cdot \frac{b}{\xi} \\
 &\geq [l\varphi_q \left(\int_0^{\delta} a(r)dr \right) + l\varphi_q \left(\int_{1-\delta}^1 a(r)dr \right) + \delta K] \cdot \frac{b}{\xi} \\
 &\geq 2\xi \cdot \frac{b}{\xi} \\
 &= 2b, \quad \text{if } \delta \leq \sigma \leq 1-\delta.
 \end{aligned}$$

Hence, condition (ii) is satisfied.

Finally, we verify that (iii) of Lemma 2.1 is also satisfied. We note that $u(t) \equiv \frac{a}{4}, 0 \leq t \leq 1$, is a member of $P(\alpha, a)$ and $\alpha(u) = \frac{a}{4} < a$. So $P(\alpha, a) \neq \emptyset$. Now, let $u \in \partial P(\alpha, a)$, then $\alpha(u) = \max_{0 \leq t \leq 1} u(t) = a$. This means that

$$0 \leq u(t) \leq a, \quad 0 \leq t \leq 1.$$

From assumption (H_6) , we have

$$f(s, \omega(s)) < \varphi_p\left(\frac{a}{\eta}\right), \quad 0 \leq s \leq 1.$$

As before, we get

$$\begin{aligned} \alpha(Tu) &= \max_{0 \leq t \leq 1} Tu(t) = Tu(\sigma) \\ &= B_0 \circ \varphi_q\left(\int_0^\sigma a(r)f(r, u(r))dr\right) + \int_0^\sigma \varphi_q\left(\int_s^\sigma a(r)f(r, u(r))dr\right)ds \\ &\leq L\varphi_q\left(\int_0^\sigma a(r)f(r, u(r))dr\right) + \int_0^\delta \varphi_q\left(\int_s^\delta a(r)f(r, u(r))dr\right)ds \\ &< (L + \delta)\varphi_q\left(\int_0^\delta a(r)dr\right) \cdot \frac{a}{\eta} \\ &< (L + 1 - \delta)\varphi_q\left(\int_0^\delta a(r)dr\right) \cdot \frac{a}{\eta} \\ &\leq a, \quad \text{if } \sigma < \delta, \end{aligned}$$

$$\begin{aligned} \alpha(Tu) &= Tu(\sigma) \\ &= B_1 \circ \varphi_q\left(\int_\sigma^1 a(r)f(r, u(r))dr\right) + \int_\sigma^1 \varphi_q\left(\int_\sigma^s a(r)f(r, u(r))dr\right)ds \\ &\leq L\varphi_q\left(\int_{1-\delta}^1 a(r)f(r, u(r))dr\right) + \int_{1-\delta}^1 \varphi_q\left(\int_{1-\delta}^s a(r)f(r, u(r))dr\right)ds \\ &= (L + \delta)\varphi_q\left(\int_{1-\delta}^1 a(r)f(r, u(r))dr\right) \\ &< (L + \delta)\varphi_q\left(\int_{1-\delta}^1 a(r)dr\right) \cdot \frac{a}{\eta} \\ &< (L + 1 - \delta)\varphi_q\left(\int_0^\delta a(r)dr\right) \cdot \frac{a}{\eta} \\ &\leq a, \quad \text{if } \sigma > 1 - \delta, \end{aligned}$$

$$\begin{aligned} 2\alpha(Tu) &= 2Tu(\sigma) \\ &= B_0 \circ \varphi_q\left(\int_0^\sigma a(r)f(r, u(r))dr\right) + \int_0^\sigma \varphi_q\left(\int_s^\sigma a(r)f(r, u(r))dr\right)ds + \\ &\quad B_1 \circ \varphi_q\left(\int_\sigma^1 a(r)f(r, u(r))dr\right) + \int_\sigma^1 \varphi_q\left(\int_\sigma^s a(r)f(r, u(r))dr\right)ds \\ &\leq L\varphi_q\left(\int_0^{1-\delta} a(r)f(r, u(r))dr\right) + \int_0^{1-\delta} \varphi_q\left(\int_0^{1-\delta} a(r)f(r, u(r))dr\right)ds + \\ &\quad L\varphi_q\left(\int_\delta^1 a(r)f(r, u(r))dr\right) + \int_\delta^1 \varphi_q\left(\int_\delta^s a(r)f(r, u(r))dr\right)ds \end{aligned}$$

$$\begin{aligned}
&= (L+1-\delta)[\varphi_q(\int_0^{1-\delta} a(r)f(r, u(r))dr) + \varphi_q(\int_\delta^1 a(r)f(r, u(r))dr)] \\
&< (L+1-\delta)[\varphi_q(\int_0^{1-\delta} a(r)dr) + \varphi_q(\int_\delta^1 a(r)dr)] \cdot \frac{a}{\eta} \\
&\leq 2a, \quad \text{if } \sigma \in [\delta, 1-\delta].
\end{aligned}$$

Therefore, BVP(1)(2) has at least three positive solutions u_1, u_2 and u_3 such that

$$0 \leq \alpha(u_1) < a < \alpha(u_2), \quad \beta(u_2) < b < \beta(u_3), \quad \gamma(u_3) < c.$$

Remark If we add the condition of $a(t)f(t, u) \not\equiv 0$, $t \in [0, 1]$, to Theorem 3.1, we can get positive solutions u_1, u_2 and u_3 such that

$$0 < \alpha(u_1) < a < \alpha(u_2), \quad \beta(u_2) < b < \beta(u_3), \gamma(u_3) < c.$$

4. An example

In this section, we present a simple example to explain our results.

Consider the boundary value problem

$$(\varphi_{\frac{3}{2}}(u'))' + a(t)f(t, u) = 0, \quad (4)$$

$$u(0) - B_0(u'(0)) = 0, \quad u(1) + B_1(u'(1)) = 0, \quad (5)$$

where

$$\begin{aligned}
f(t, u) &= \begin{cases} 60, & 0 \leq t \leq 1, \quad 0 \leq u \leq 5, \\ u + 55, & 0 \leq t \leq 1, \quad 5 \leq u \leq 36, \\ 91, & 0 \leq t \leq 1, \quad 36 \leq u \leq 10^4, \\ 91 + \frac{u-10^4}{\sqrt{u}}, & 0 \leq t \leq 1, \quad u \geq 10^4. \end{cases} \\
a(t) &= \begin{cases} t, & 0 \leq t \leq \frac{1}{2} \\ 1-t, & \frac{1}{2} \leq t \leq 1 \end{cases}
\end{aligned}$$

In the example, we notice that $B_0(v) = B_1(v) = \frac{1}{2}v$, $l = L = \frac{1}{2}$, $p = \frac{3}{2}$, and $q = 3$. Choose $\delta = \frac{1}{4}$. It follows from a direct calculation that

$$\begin{aligned}
K &= \min_{\frac{1}{4} \leq x \leq 1 - \frac{1}{4}} y(x) = \frac{18}{32^2}, \\
\eta &= \max\{(\frac{1}{2} + 1 - \frac{1}{4})\varphi_3(\int_0^{\frac{1}{4}} r dr), (\frac{1}{2} + 1 - \frac{1}{4})\varphi_3(\int_{\frac{3}{4}}^1 (1-r) dr)\} = \frac{5}{4} \times (\frac{1}{32})^2 \\
\xi &= \min\{\frac{67}{2} \times (\frac{1}{32})^2, \frac{67}{2} \times (\frac{1}{32})^2, \frac{11}{4} \times (\frac{1}{32})^2\} = \frac{11}{4} \times (\frac{1}{32})^2, \\
\lambda &= (\frac{1}{2} + 1 - \frac{1}{4})\varphi_3(\int_0^1 a(r) dr) = \frac{5}{64}.
\end{aligned}$$

Here we choose $a = 5$, $b = 9$, $c = 2500$, then we get

$$f(t, u) = 60 < 64 = \varphi_{\frac{3}{2}}(4 \times 32^2) = \varphi_{\frac{3}{2}}(\frac{a}{\eta}), \quad \frac{1}{4} \leq t \leq 1 - \frac{1}{4}, \quad 0 \leq u \leq 5,$$

$$f(t, u) \geq 60 > \frac{192}{\sqrt{11}} = \varphi_{\frac{3}{2}}\left(\frac{9}{\frac{11}{4} \times (\frac{1}{32})^2}\right) = \varphi_{\frac{3}{2}}\left(\frac{b}{\xi}\right), \quad 0 \leq t \leq 1, \quad 0 \leq u \leq 36,$$

$$f(t, u) = 91 < 80\sqrt{5} = \varphi_{\frac{3}{2}}\left(\frac{2500}{\frac{5}{64}}\right) = \varphi_{\frac{3}{2}}\left(\frac{c}{\lambda}\right), \quad 0 \leq t \leq 1, \quad 625 \leq u \leq 10^4.$$

Then all the conditions of Lemma 2.1 are satisfied. So, by Theorem 3.1, we know BVP(4)(5) has at least three positive solutions.

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p -Laplace 非线性两点边值问题多个正解的存在性

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摘要: 本文利用一种新的三个泛函不动点定理得到了 p -Laplacian 方程在具有非线性边值条件时至少存在三个正解的充分条件, 并且举了一个简单例子来说明得到的结论.

关键词: 边值问题; p -Laplacian 算子; 正解; 三个泛函不动点定理.