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# Some Properties of Cauchy-type Singular Integral Operator on Unbounded Domains

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**Abstract** On the basis of introducing the modified Cauchy kernel, we discuss the Hölder continuity of the Cauchy-type singular integral operator on unbounded domains for regular functions by dividing into the following three cases: two points are on the boundary of region; one point is on the boundary and another point is in the interior(or exterior) of the region; two points are in the interior (or exterior) of the region.

**Keywords** regular function; Cauchy-type singular integral operator; unbounded domains; Hölder continuity.

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### 1. Introduction

Clifford algebra  $\mathcal{A}_n(R)$  was established by Clifford [1] in 1878, which is the extension of the plural, quaternion and exterior algebras. It possesses both theoretical and applicable values in many fields, such as quantum field theory [2], computer graphics [3], neural network [4] and so on. Clifford analysis is an important branch of modern analysis that studies functions defined on  $R^{n+1}$  and valued in Clifford algebra space  $\mathcal{A}_n(R)$ . Since 1970, on the basis of Dirac operator, Brackx, Delanghe, Sommen [5] etc. put forward the regular function, which is an extension of the holomorphic function in higher dimensional space and has been investigated by many scholars such as Xu [6], Wen [7], Huang, Qiao [8,9] etc. In addition, because many problems in the actual application are proposed in the case of unbounded domains, Klaus Gürlebeck, Uwe Kähler, John Ryan [10] introduced the modified Cauchy kernel in 1997, which makes it possible to study the Cauchy integral on unbounded domains and have obtained a series of results such as the integral representation of the regular function and Plemelj formulae etc.

Cauchy-type integral operator is a singular integral operator and it is the core components of the solution of the boundary value problem. Its localized properties are the theoretical basis of the boundary value problem of the analytic function and generalized analytic function. Furthermore, the latter is closely related with the elasticity mechanics, shell theory and the air

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dynamics etc. Thus there are many scholars who have carried a lot of research for it. For example, Lu [11] researched the properties and the corresponding boundary value problem of the Cauchy-type integral operator and Cauchy-type singular integral for density function containing parameter in complex plane. Gilbert [12] studied some properties and applications of Cauchy type integral operators and higher dimensional singular integral operators. Gong [13] discussed the stabilities of Cauchy-type singular integral operator when the boundary curve of integral domain is perturbed. In addition, because Clifford analysis is the extension of complex analysis, studying the properties of all kinds of singular integral operators has been a hot and significant topics in Clifford analysis. Yang [14] and Qiao [15], for example, have studied some properties of some singular integral operators and the corresponding boundary value problem in Quaternion analysis and Clifford analysis, respectively.

On the basis of the above reference, this article studies some properties of the Cauchy-type singular integral operator on unbounded domains. For example, we discuss the Hölder continuity of the Cauchy-type singular integral operator on unbounded domains for regular functions by dividing into the following three cases: two points are on the boundary of region; one point is on the boundary and another point is in the interior (or exterior) of the region; two points are in the interior (or exterior) of the region.

### 2. Preliminaries

Let  $e_0, e_1, \ldots, e_n$  be an orthogonal basis of the Euclidean space  $R^{n+1}$  and  $\mathcal{A}_n(R)$  be the  $2^n$ -dimensional Clifford algebra with basis  $\{e_A : e_A = e_{\alpha_1} \cdots e_{\alpha_h}\}$ , where  $A = \{\alpha_1, \ldots, \alpha_h\} \subseteq \{1, \ldots, n\}, 1 \leq \alpha_1 < \alpha_2 < \cdots < \alpha_h \leq n$  and  $e_{\emptyset} = e_0 = 1$ . The associative and noncommutative multiplication of the basis in  $\mathcal{A}_n(R)$  is governed by the rules  $e_i^2 = -1$   $(i = 1, 2, \ldots, n), e_i e_j = -e_j e_i (1 \leq i, j \leq n, i \neq j), e_0 e_i = e_i e_0 = e_i (i = 0, 1, \ldots, n)$ . Hence the real Clifford algebra is composed of elements having the type  $a = \sum_A x_A e_A, x_A \in R$ . The norm for an element  $a \in \mathcal{A}_n(R)$  is taken to be  $|a| = (\sum_A |x_A|^2)^{\frac{1}{2}}$ , and satisfies  $|\overline{a}| = |a|, |a + b| \leq |a| + |b|, |ab| \leq 2^n |a| |b|$ .

Let  $U \subset \mathbb{R}^{n+1}$  be a domain. The function f which is defined in U with values in  $\mathcal{A}_n(\mathbb{R})$ can be expressed as  $f(x) = \sum_A f_A(x)e_A$ , where all  $f_A(x)$  are real-valued functions. Let  $f(x) \in C^{(r)}(U, \mathcal{A}_n(\mathbb{R})) = \{f | f : U \to \mathcal{A}_n(\mathbb{R}), f(x) = \sum_A f_A(x)e_A, f_A(x) \in C^r(U)\}$ . And the Dirac operator is defined as

$$D_l(f) = \sum_{i=0}^n e_i \frac{\partial f}{\partial x_i} = \sum_{i=0}^n \sum_A e_i e_A \frac{\partial f_A}{\partial x_i}, \quad D_r(f) = \sum_{i=0}^n \frac{\partial f}{\partial x_i} e_i = \sum_{i=0}^n \sum_A \frac{\partial f_A}{\partial x_i} e_A e_i.$$

If  $D_l(f) = 0(D_r(f) = 0)$ , then f is called a left (right) regular function.

In addition, denoting

$$d\hat{x}_i = dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \dots \wedge dx_n, \quad i = 1, 2, \dots, n,$$
$$d\sigma = \sum_{i=1}^n (-1)^{i-1} e_i d\hat{x}_i, \quad \overrightarrow{n} = \sum_{i=1}^n e_i n_i,$$

where  $n_i$  is *i*-th component of the unit outward normal vector  $\vec{n}$  and  $d\sigma = \vec{n} ds$ . ds is the surface element and  $dx^n = dx_1 \wedge \cdots \wedge dx_n$  is the volume element.

Next let  $U \subset \mathbb{R}^{n+1}$  be unbounded domains whose complement contains an internal point, and the boundary  $\partial U$  be a differentiable, oriented and compact Liapunov surface.

Since  $\partial U$  is a Liapunov surface, from the corresponding proof in [8], we have

$$|\mathrm{d}\sigma| = |\mathrm{d}s| = \Big|\frac{D(\xi_0, \xi_1, \dots, \xi_{n-1})}{D(\rho_0, \varphi_1, \dots, \varphi_{n-1})}\Big| |\mathrm{d}\rho_0 \mathrm{d}\varphi_1 \mathrm{d}\varphi_2 \cdots \mathrm{d}\varphi_{n-1}| \le M_0 \rho_0^{n-1} \mathrm{d}\rho_0,$$

where  $M_0 > 0$  is a real constant number.

**Definition 2.1** Let  $U, \partial U$  be as stated above. The integral

$$(T_{\partial U}[f])(x) = \frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x) \mathrm{d}\sigma(y) f(y)$$
(2.1)

is called Cauchy-type singular integral operator on unbounded domains, where n(y) is the normal vector through y,  $l(y,x) = \frac{\overline{y}-\overline{x}}{|y-x|^{n+1}} - \frac{\overline{y}-\overline{z}}{|y-z|^{n+1}}$  is a modified Cauchy kernel, z is a given point in the complement of  $\overline{U}$  and  $\omega_{n+1}$  is the area of the unit sphere in  $\mathbb{R}^{n+1}$ . When  $x \notin \partial U$ , it is clear that the integral is well defined. When  $x \in \partial U$ , it is a singular integral on unbounded domains.

**Definition 2.2** Let  $U, \partial U$  be as stated above and  $x_0 \in \partial U$ . We construct a sphere E with the center at  $x_0$  and radiu  $\delta > 0$ . Then  $\partial U$  is divided into two parts by E and the part of  $\partial U$  lying in the interior of E is denoted by  $\lambda_{\delta}$ . Suppose

$$(T_{\partial U}[f])_{\delta}(x_0) = \frac{1}{\omega_{n+1}} \int_{\partial U - \lambda_{\delta}} l(y, x_0) \mathrm{d}\sigma(y) f(y).$$
(2.2)

If  $\lim_{\delta \to 0} (T_{\partial U}[f])_{\delta}(x_0) = I(x_0)$ , then  $I(x_0)$  is called the Cauchy principal value of singular integral  $(T_{\partial U}[f])(x_0)$  and we denote that  $I(x_0) = (T_{\partial U}[f])(x_0)$ .

**Remark** When  $f : \partial U \to \mathcal{A}_n(R)$  is both bounded and Hölder continuous with exponent  $\alpha \in (0, 1)$ , the above Cauchy principal value of singular integral is well defined for each  $x_0 \in \partial U$ .

**Lemma 2.3** ([10]) There exists the positive constant C(n) > 0, such that

$$|l(y,x)| \le C(n)|x-z| \sum_{j=1}^{n} |y-x|^{-j}|y-z|^{j-(n+1)}.$$

**Lemma 2.4** ([10]) Let  $U, \partial U$  be as stated above. If f(x) is a bounded, left regular function on U and extends continuously in the  $L^{\infty}$  sense to the boundary of U. Then, we have

$$\frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x) \mathrm{d}\sigma(y) f(y) = \begin{cases} f(x), & x \in U, \\ 0, & x \in R^{n+1} - \bar{U}. \end{cases}$$

**Lemma 2.5** ([10]) Let  $U, \partial U$  be as stated above. Then, in the sense of cauchy principal value, we have

$$\frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x_0) \mathrm{d}\sigma(y) = \frac{1}{2}, \ x_0 \in \partial U.$$

**Lemma 2.6** ([10]) Let  $U, \partial U$  be as stated above,  $f \in H^{\alpha}_{\partial U}$  ( $0 < \alpha < 1$ ), f be bounded and  $x_0 \in \partial U$ . Suppose  $(T_{\partial U}[f])^+(x_0) = \lim_{x \to x_0, x \in U^+} (T_{\partial U}[f])(x), (T_{\partial U}[f])^-(x_0) = \lim_{x \to x_0, x \in U^-} (T_{\partial U}[f])(x),$  where  $U^+, U^-$  are the interior and exterior of U, respectively. Then, in the sense of cauchy prin-

cipal value, we have

$$(T_{\partial U}[f])^{+}(x_{0}) = \frac{1}{2}f(x_{0}) + (T_{\partial U}[f])(x_{0}),$$
  
$$(T_{\partial U}[f])^{-}(x_{0}) = -\frac{1}{2}f(x_{0}) + (T_{\partial U}[f])(x_{0}).$$

**Lemma 2.7** ([16]) (1) If  $\varphi \in H^{\alpha}_{\partial U}$ ,  $0 < \beta \leq \alpha < 1$ , then  $\varphi \in H^{\beta}_{\partial U}$ ; (2) If  $f_1(x), f_2(x) \in H^{\alpha}_{\partial U}$ , then  $f_1(x) \pm f_2(x) \in H^{\alpha}_{\partial U}$ ; (3) Let  $f(x) = \sum_A f_A(x)e_A$ . If  $f_A(x) \in H^{\alpha}_{\partial U}$ , then  $f \in H^{\alpha}_{\partial U}, 0 < \alpha < 1$ .

## 3. The Hölder continuity of the singular integral operator

**Theorem 3.1** Let  $U, \partial U, U^-$  and  $(T_{\partial U}[f])^-$  be stated as before,  $\Omega \subseteq \mathbb{R}^{n+1}$  be a bounded domain and  $\Omega \cap \partial U \neq \emptyset$ . If  $f \in H^{\alpha}_{\partial U}(0 < \alpha < 1)$  and f is bounded. Then, in the sense of cauchy principal value, we have

(1)  $(T_{\partial U}[f])^- \in H^{\alpha}_{\partial U \cap \Omega}$ , namely, there exists  $M_1 > 0$  such that for any  $x_1, x_2 \in \partial U \cap \Omega$ ,  $(T_{\partial U}[f])^-$  satisfies

$$|(T_{\partial U}[f])^{-}(x_1) - (T_{\partial U}[f])^{-}(x_2)| \le M_1 |x_1 - x_2|^{\alpha}.$$

(2)  $||(T_{\partial U}[f])^-||_{\alpha} \leq J ||f||_{\alpha}$ , where J is a constant independent of f.

**Proof** (1) For any  $x_1, x_2 \in \partial U \cap \Omega$ , let  $|x_1 - x_2| = \delta$ . Firstly, we suppose  $6\delta < d$ , where d is the same as the one in the definition of Liapunov surface. Because the following formula is right

$$\lim_{|y| \to \infty} \frac{|y - x_2|}{|y - z|} = 1,$$

we may construct a sphere  $E_1$  with the center at  $x_1$  and radius  $3\delta$ , and construct a sphere  $E_2$ with the center at  $x_1$  and radius R, where R is big enough. The part of  $\partial U$  lying in the interior of  $E_1$  is denoted by  $\partial U_1$ , the part of  $\partial U$  lying between  $E_1$  and  $E_2$  is denoted by  $\partial U_2$  and the part of  $\partial U$  lying in the exterior  $E_2$  is denoted by  $\partial U_3$ . We take R to be big enough in order to guarantee the following formula is right on  $\partial U_3$ .

$$|y - x_2| \le L_1 |y - z|, \tag{3.1}$$

where  $L_1 > 0$  is an constant number.

In addition, by  $|y - x_1| \leq |y - x_2| + |x_2 - x_1|, |y - x_2| \leq |y - x_1| + |x_1 - x_2|$  and  $|y - x_1| > 3\delta(y \in \partial U - \partial U_1)$ , we know the following formula is right on both  $\partial U_2$  and  $\partial U_3$ .

$$\frac{1}{2} \le \frac{|y - x_2|}{|y - x_1|} \le 2.$$
(3.2)

By Lemmas 2.5 and 2.6, we have

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$$\left| \int_{\partial U_2} l(y, x_1) d\sigma(y) [f(y) - f(x_1)] - \int_{\partial U_2} l(y, x_2) d\sigma(y) [f(y) - f(x_2)] \right| + \left| \int_{\partial U_3} l(y, x_1) d\sigma(y) [f(y) - f(x_1)] - \int_{\partial U_3} l(y, x_2) d\sigma(y) [f(y) - f(x_2)] \right|$$
  
$$\leq J_1 (I_1 + I_2 + I_3 + I_4).$$
(3.3)

Firstly, in the case of  $3\delta < 6\delta < d$ . Then, because  $\frac{y-x_1}{y-z}$  and  $\frac{x_1-z}{y-z}$  are continuous on  $\partial U_1$ , there exist constants  $L_2, L_3 > 0$ , such that the following formula is right for any  $y \in \partial U_1$ .

$$|y - x_1| < L_2|y - z|, |x_1 - z| < L_3|y - z|$$

Again by lemma 2.3, we have

$$\begin{aligned} |l(y,x_1)| &\leq C(n)|x_1 - z| \sum_{j=1}^n |y - x_1|^{-j} |y - z|^{j - (n+1)} \\ &\leq C(n)J_2|y - z| \sum_{j=1}^n |y - x_1|^{-j} |y - z|^{j - (n+1)} \\ &= C(n)J_3 \sum_{j=1}^n |y - x_1|^{-j} |y - z|^{j - n} \\ &\leq C(n)J_3 \sum_{j=1}^n |y - x_1|^{-j} (\frac{1}{L_2})^{j - n} |y - x_1|^{j - n} = J_4 |y - x_1|^{-n}. \end{aligned}$$

Hence, by  $f\in H^{\alpha}_{\partial U}$  and local generalized spherical coordinate, we obtain

$$I_{1} = \left| \int_{\partial U_{1}} l(y, x_{1}) d\sigma(y) [f(y) - f(x_{1})] \right|$$
  

$$\leq J_{5} H(f, \partial U, \alpha) \int_{\partial U_{1}} |y - x_{1}|^{-n+\alpha} |d\sigma(y)|$$
  

$$\leq J_{6} H(f, \partial U, \alpha) \int_{0}^{3\delta} \rho_{0}^{\alpha-1} d\rho_{0} = J_{7} H(f, \partial U, \alpha) |x_{1} - x_{2}|^{\alpha}.$$
(3.4)

Similarly, we have

$$I_2 \le J_8 H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha}.$$

$$(3.5)$$

Next, we calculate  $I_3$ ,

$$\begin{split} I_{3} &= \Big| \int_{\partial U_{2}} l(y,x_{1}) \mathrm{d}\sigma(y) [f(y) - f(x_{1})] - \int_{\partial U_{2}} l(y,x_{2}) \mathrm{d}\sigma(y) [f(y) - f(x_{2})] \Big| \\ &= \Big| \int_{\partial U_{2}} [l(y,x_{1}) - l(y,x_{2})] \mathrm{d}\sigma(y) [f(y) - f(x_{1})] + \int_{\partial U_{2}} l(y,x_{2}) \mathrm{d}\sigma(y) [f(x_{2}) - f(x_{1})] \Big| \\ &\leq \Big[ \Big| \int_{\partial U_{2}} [\frac{\overline{y} - \overline{x_{1}}}{|y - x_{1}|^{n+1}} - \frac{\overline{y} - \overline{x_{2}}}{|y - x_{2}|^{n+1}}] \mathrm{d}\sigma(y) [f(y) - f(x_{1})] \Big| + \\ &\quad \Big| \int_{\partial U_{2}} \frac{\overline{y} - \overline{x_{2}}}{|y - x_{2}|^{n+1}} \mathrm{d}\sigma(y) [f(x_{2}) - f(x_{1})] \Big| \Big] + \\ &\quad \Big| \int_{\partial U_{2}} \frac{\overline{y} - \overline{z}}{|y - z|^{n+1}} \mathrm{d}\sigma(y) [f(x_{2}) - f(x_{1})] \Big| \\ &= I_{31} + I_{32}. \end{split}$$

By [17], we have  $I_{31} \leq J_9 H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha}$ . In addition, for  $I_{32}$ , because the integral has no singularity on bounded domain  $\partial U_2$ , it is well defined. There is no harm to suppose  $|\int_{\partial U_2} \frac{\overline{y}-\overline{z}}{|y-z|^{n+1}} d\sigma(y)| = J_{10}$ . Thus we have

$$I_{32} \le J_{10}H(f,\partial U,\alpha)|x_1 - x_2|^{\alpha}.$$

 $\operatorname{So}$ 

$$I_3 \le J_{11}H(f, \partial U, \alpha)|x_1 - x_2|^{\alpha}.$$
 (3.6)

Finally, we calculate  $I_4$ ,

$$\begin{split} I_4 &= \Big| \int_{\partial U_3} l(y, x_1) \mathrm{d}\sigma(y) [f(y) - f(x_1)] - \int_{\partial U_3} l(y, x_2) \mathrm{d}\sigma(y) [f(y) - f(x_2)] \Big| \\ &\leq \Big| \int_{\partial U_3} [l(y, x_1) - l(y, x_2)] \mathrm{d}\sigma(y) [f(y) - f(x_1)] \Big| + \Big| \int_{\partial U_3} l(y, x_2) \mathrm{d}\sigma(y) [f(x_2) - f(x_1)] \Big| \\ &= I_{41} + I_{42}. \end{split}$$

From Hile's lemma [2], we get

$$|l(y, x_1) - l(y, x_2)| = \left| \frac{\overline{y} - \overline{x_1}}{|y - x_1|^{n+1}} - \frac{\overline{y} - \overline{x_2}}{|y - x_2|^{n+1}} \right|$$
  
$$\leq \sum_{k=0}^{n-1} \left| \frac{y - x_1}{y - x_2} \right|^{-(k+1)} |y - x_2|^{-(n+1)} |x_1 - x_2|.$$
(3.7)

Again by (3.2), we have

$$I_{41} \leq \int_{\partial U_3} \sum_{k=0}^{n-1} 2^{k+1} \left| \frac{y - x_1}{y - x_2} \right|^{\alpha} \frac{1}{|y - x_2|^{n+1-\alpha}} H(f, \partial U, \alpha) |x_1 - x_2| |d\sigma(y)|$$
  
$$\leq J_{12} H(f, \partial U, \alpha) |x_1 - x_2| \int_R^{+\infty} \rho_0^{\alpha - 2} d\rho_0 \leq J_{13} H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha}.$$

For  $I_{42}$ , from Lemma 2.3, (3.1), (3.2) and the boundedness of the region  $\Omega$ , we obtain

$$\begin{aligned} |l(y,x_2)| &\leq C(n)|x_2 - z| \sum_{j=1}^n |y - x_2|^{-j} |y - z|^{j - (n+1)} \\ &\leq C(n)|x_2 - z| \sum_{j=1}^n |y - x_2|^{-j} (\frac{1}{M_2})^{j - (n+1)} |y - x_2|^{j - (n+1)} \\ &\leq J_{14}|y - x_2|^{-(n+1)} \leq J_{15}|y - x_1|^{-(n+1)}. \end{aligned}$$

Thus

$$\begin{split} I_{42} &= \left| \int_{\partial U_3} l(y, x_2) \mathrm{d}\sigma(y) [f(x_2) - f(x_1)] \right| \\ &\leq J_{16} H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha} \int_{\partial U_3} |y - x_1|^{-(n+1)} |\mathrm{d}\sigma(y)| \\ &\leq J_{17} H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha} \int_R^{+\infty} \rho_0^{-2} \mathrm{d}_{\rho_0} = J_{18} H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha}. \end{split}$$

 $\operatorname{So}$ 

$$I_4 \le J_{19} H(f, \partial U, \alpha) |x_1 - x_2|^{\alpha}.$$
 (3.8)

Hence, by (3.3)-(3.8), we get

$$|(T_{\partial U}[f])^{-}(x_{1}) - (T_{\partial U}[f])^{-}(x_{2})| \le J_{20}H(f,\partial U,\alpha)|x_{1} - x_{2}|^{\alpha} \le J_{21}||f||_{\alpha}|x_{1} - x_{2}|^{\alpha}.$$
 (3.9)

Namely, when  $6|x_1 - x_2| < d$ ,  $(T_{\partial U}[f])^- \in H^{\alpha}_{\partial U \cap \Omega}$ .

Secondly, when  $6|x_1 - x_2| \ge d$ . By Lemmas 2.5 and 2.6, we know for arbitrary given  $x \in \partial U \cap \Omega$ ,

$$|(T_{\partial U}[f])^{-}(x)| = |(T_{\partial U}[f])(x) - \frac{1}{2}f(x)|$$

$$= \frac{1}{\omega_{n+1}} \left| \int_{\partial U} l(y,x) \mathrm{d}\sigma(y)[f(y) - f(x)] \right|$$

$$\leq \frac{1}{\omega_{n+1}} H(f, \partial U, \alpha) \int_{\partial U} |l(y,x)| |y - x|^{\alpha} |\mathrm{d}\sigma(y)|. \tag{3.10}$$

Again

$$\lim_{|y|\to\infty}\frac{|y-x|}{|y-z|}=1.$$

Hence, there exists a constant r > 0 such that the following formula is right for any  $y \in \partial U - \lambda_r$ .

$$|y - x| \le L_4 |y - z|, \tag{3.11}$$

where  $\lambda_r = B(x, r) \cap \partial U$  and  $L_4 > 0$  is a constant number. Thus

$$\int_{\partial U} |l(y,x)||y-x|^{\alpha} |\mathrm{d}\sigma(y)| = \int_{\lambda_r} |l(y,x)||y-x|^{\alpha} |\mathrm{d}\sigma(y)| + \int_{\partial U-\lambda_r} |l(y,x)||y-x|^{\alpha} |\mathrm{d}\sigma(y)|$$
$$= O_1 + O_2.$$

Again

$$\begin{split} O_1 &= \int_{\lambda_r} |l(y,x)| |y-x|^{\alpha} |\mathrm{d}\sigma(y)| \\ &\leq \int_{\lambda_r} \frac{|\overline{y}-\overline{x}|}{|y-x|^{n+1}} |y-x|^{\alpha} |\mathrm{d}\sigma(y)| + \int_{\lambda_r} \frac{|\overline{y}-\overline{z}|}{|y-z|^{n+1}} |y-x|^{\alpha} |\mathrm{d}\sigma(y)| \\ &= O_{11} + O_{12}. \end{split}$$

For  $O_{11}$ , by the local generalized spherical coordinate, we know it is convergent. For  $O_{12}$ , because it is normal integral on bounded domain, it is convergent. So there is no harm to suppose

$$O_1 \le J_{22}.$$
 (3.12)

For  $O_2$ , by Lemma 2.3, (3.11), the boundedness of the region  $\Omega$  and the local generalized spherical coordinate, we have

$$O_{2} = \int_{\partial U - \lambda_{r}} |l(y, x)| |y - x|^{\alpha} |d\sigma(y)|$$

$$\leq \int_{\partial U - \lambda_{r}} C(n) |x - z| \sum_{j=1}^{n} |y - x|^{-j} |y - z|^{j - (n+1)} |y - x|^{\alpha} |d\sigma(y)|$$

$$\leq J_{23} \int_{\partial U - \lambda_{r}} |y - x|^{\alpha - (n+1)} |d\sigma(y)| \leq J_{24} \int_{\partial U - \lambda_{r}} \rho_{0}^{\alpha - 2} d\rho_{0} = J_{25}.$$
(3.13)

Thus by (3.10), (3.12) and (3.13), we get

$$|(T_{\partial U}[f])^{-}(x)| \le J_{26}H(f, \partial U, \alpha) \le J_{26}||f||_{\alpha}.$$
(3.14)

So, when  $6|x_1 - x_2| \ge d$ , we have

$$|(T_{\partial U}[f])^{-}(x_{1}) - (T_{\partial U}[f])^{-}(x_{2})| \leq |(T_{\partial U}[f])^{-}(x_{1})| + |(T_{\partial U}[f])^{-}(x_{2})| \\ \leq 2J_{26} ||f||_{\alpha} 6^{\alpha} \frac{|x_{1} - x_{2}|^{\alpha}}{d^{\alpha}} \leq J_{27} ||f||_{\alpha} |x_{1} - x_{2}|^{\alpha}.$$
(3.15)

Namely, when  $6|x_1 - x_2| \ge d$ ,  $(T_{\partial U}[f])^- \in H^{\alpha}_{\partial U \cap \Omega}$ . Hence, we have

$$(T_{\partial U}[f])^- \in H^{\alpha}_{\partial U \cap \Omega}, \quad 0 < \alpha < 1.$$

(2) From (3.14), we know

$$\max_{x \in \partial U \cap \Omega} |(T_{\partial U}[f])^{-}(x)| \le J_{26} ||f||_{\alpha}.$$

In addition, from (3.9) and (3.15), we get

$$\sup_{1,x_2 \in \partial U \cap \Omega, x_1 \neq x_2} \frac{|(T_{\partial U}[f])^-(x_1) - (T_{\partial U}[f])^-(x_2)|}{|x_1 - x_2|^{\alpha}} \le J_{28} ||f||_{\alpha}.$$

So,  $||(T_{\partial U}[f])^-(x)||_{\alpha} \leq J_{29}||f||_{\alpha}$ . Taking  $J = J_{29}$ , we get  $||(T_{\partial U}[f])^-(x)||_{\alpha} \leq J||f||_{\alpha}$ , where J is a constant independent of f.  $\Box$ 

**Theorem 3.2** Let  $U, \partial U, U^-$  and  $\Omega$  be stated as above. If  $f \in H^{\alpha}_{\partial U}(0 < \alpha < 1)$  and f is bounded. Then we can obtain

- (1)  $T_{\partial U}[f] \in H^{\alpha}_{\partial U \cap \Omega}$ .
- (2)  $||T_{\partial U}[f]||_{\alpha} \leq J' ||f||_{\alpha}$ , where J' is a constant independent of f.

**Proof** From Lemma 2.6, we know

$$(T_{\partial U}[f])(x) = (T_{\partial U}[f])^{-}(x) + \frac{1}{2}f(x), \quad x \in \partial U \cap \Omega.$$

Again by Theorem 3.1, we have  $(T_{\partial U}[f])^- \in H^{\alpha}_{\partial U \cap \Omega}$ . Hence, by Lemma 2.7, we get  $T_{\partial U}[f] \in H^{\alpha}_{\partial U \cap \Omega}$ .

(2) From Lemma 2.6, we know  $|(T_{\partial U}[f])(x)| = |(T_{\partial U}[f])^{-}(x) + \frac{1}{2}f(x)|$ . Thus

$$\max_{x \in \partial U \cap \Omega} |(T_{\partial U}[f])(x)| \le \max_{x \in \partial U \cap \Omega} |(T_{\partial U}[f])^{-}(x)| + \frac{1}{2} \max_{x \in \partial U} |f(x)|$$

Again by Lemma 2.6, we have

$$\begin{aligned} |(T_{\partial U}[f])(x_1) - (T_{\partial U}[f])(x_2)| \\ &= |(T_{\partial U}[f])^-(x_1) + \frac{1}{2}f(x_1) - (T_{\partial U}[f])^-(x_2) - \frac{1}{2}f(x_2)| \\ &\leq |(T_{\partial U}[f])^-(x_1) - (T_{\partial U}[f])^-(x_2)| + \frac{1}{2}|f(x_1) - f(x_2)|. \end{aligned}$$

 $\operatorname{So}$ 

$$\sup_{\substack{x_1, x_2 \in \partial U \cap \Omega, x_1 \neq x_2 \\ \leq x_1, x_2 \in \partial U \cap \Omega, x_1 \neq x_2 }} \frac{|(T_{\partial U}[f])(x_1) - (T_{\partial U}[f])(x_2)|}{|x_1 - x_2|^{\alpha}} \\ \leq \sup_{\substack{x_1, x_2 \in \partial U \cap \Omega, x_1 \neq x_2 \\ q = x_1 + x_2 = x_2}} \frac{|(T_{\partial U}[f])^-(x_1) - (T_{\partial U}[f])^-(x_2)|}{|x_1 - x_2|^{\alpha}} + \frac{1}{2} \sup_{\substack{x_1, x_2 \in \partial U, x_1 \neq x_2 \\ q = x_2 + x_2 = x_2$$

Namely,

$$H(T_{\partial U}[f], \partial U \cap \Omega, \alpha) \le H((T_{\partial U}[f])^{-}, \partial U \cap \Omega, \alpha) + \frac{1}{2}H(f, \partial U, \alpha).$$

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 $\operatorname{So}$ 

$$\begin{aligned} \|T_{\partial U}[f]\|_{\alpha} &\leq \|(T_{\partial U}[f])^{-}\|_{\alpha} + \frac{1}{2}H(f,\partial U,\alpha) \\ &\leq J_{29}\|f\|_{\alpha} + \frac{1}{2}\|f\|_{\alpha} = J_{30}\|f\|_{\alpha}. \end{aligned}$$

Taking  $J' = J_{30}$ , we can obtain  $||T_{\partial U}[f]||_{\alpha} \leq J' ||f||_{\alpha}$ , where J' is a constant independent of f.  $\Box$ 

**Theorem 3.3** Let  $U, \partial U, U^+, \Omega$  be stated as above. If  $f \in H^{\alpha}_{\partial U}(0 < \alpha < 1)$  and f is bounded, then for any points  $x_0 \in \partial U \cap \Omega$ ,  $x \in U^+ \cap \Omega$ , we have

$$|T_{\partial U}[f](x) - (T_{\partial U}[f])^+(x_0)| \le M_2 |x - x_0|^{\alpha},$$

where  $M_2 > 0$  is a constant independent of  $x, x_0$ .

**Proof** Let  $|x - x_0| = \delta$ . We suppose  $6\delta < d$ . Similarly to the theorem 3.1, we construct a sphere  $E_1$  with the center at  $x_0$  and radius  $3\delta$ . Then we construct a sphere  $E_2$  with the center at  $x_0$  and radius R, where R is big enough. The part of  $\partial U$  lying in the interior of  $E_1$  is denoted by  $\partial U_1$ , the part of  $\partial U$  lying between  $E_1$  and  $E_2$  is denoted by  $\partial U_2$ , and the part of  $\partial U$  lying in the exterior  $E_2$  is denoted by  $\partial U_3$ . Thus by Lemmas 2.4, 2.5 and 2.6, we have

$$\begin{split} |T_{\partial U}[f](x) - (T_{\partial U}[f])^{+}(x_{0})| \\ &= |T_{\partial U}[f](x) - T_{\partial U}[f](x_{0}) - \frac{1}{2}f(x_{0})| \\ &= \left|\frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x) \mathrm{d}\sigma(y)f(y) - \frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x_{0}) \mathrm{d}\sigma(y)f(y) - \frac{1}{2}f(x_{0})\right| \\ &= \left|\frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x) \mathrm{d}\sigma(y)f(y) - f(x_{0}) + f(x_{0}) - \frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x_{0}) \mathrm{d}\sigma(y)f(y) - \frac{1}{2}f(x_{0})\right| \\ &= \left|\frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x) \mathrm{d}\sigma(y)(f(y) - f(x_{0})) + \frac{1}{2}f(x_{0}) - \frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x_{0}) \mathrm{d}\sigma(y)f(y)\right| \\ &= \left|\frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x) \mathrm{d}\sigma(y)(f(y) - f(x_{0})) + \frac{1}{\omega_{n+1}} \int_{\partial U} l(y,x_{0}) \mathrm{d}\sigma(y)(f(x_{0}) - f(y))\right| \\ &= \left|\frac{1}{\omega_{n+1}} \int_{\partial U} (l(y,x) - l(y,x_{0})) \mathrm{d}\sigma(y)(f(y) - f(x_{0}))\right| \\ &\leq \left|\frac{1}{\omega_{n+1}} \int_{\partial U_{1}} (l(y,x) - l(y,x_{0})) \mathrm{d}\sigma(y)(f(y) - f(x_{0}))\right| + \\ &\left|\frac{1}{\omega_{n+1}} \int_{\partial U_{2}} (l(y,x) - l(y,x_{0})) \mathrm{d}\sigma(y)(f(y) - f(x_{0}))\right| \\ &= I_{5} + I_{6} + I_{7}. \end{split}$$

Again, when  $y \in \partial U_1$ , the following inequalities hold.

$$|y-x| \le L_5 |y-z|, |x-z| \le L_5 |y-z|, |y-x_0| \le L_6 |y-z|, |x_0-z| \le L_6 |y-z|, |x_0-z|, |x_0-z| \le L_6 |y-z|, |x_0-z|, |x_0-$$

where  $L_5 > 0, L_6 > 0$  is a constant number.

And

$$\begin{split} I_{5} &= \left| \frac{1}{\omega_{n+1}} \int_{\partial U_{1}} (l(y,x) - l(y,x_{0})) \mathrm{d}\sigma(y) (f(y) - f(x_{0})) \right| \\ &\leq \left| \frac{1}{\omega_{n+1}} \int_{\partial U_{1}} |l(y,x)| \mathrm{d}\sigma(y)| f(y) - f(x_{0}) \right| + \left| \frac{1}{\omega_{n+1}} \int_{\partial U_{1}} |l(y,x_{0})| \mathrm{d}\sigma(y)| f(y) - f(x_{0}) \right| \\ &= I_{51} + I_{52}. \end{split}$$

So, similarly to the estimation method of  $I_1, I_2$  in Theorem 3.1, we have

 $I_{51} \le J_{31}|x-x_0|^{\alpha}, \ I_{52} \le J_{32}|x-x_0|^{\alpha}.$ 

And similarly to the estimation method of  $I_{31}$ ,  $I_{41}$  in Theorem 3.1, we have

 $I_6 \leq J_{33}|x-x_0|^{\alpha}, \ I_7 \leq J_{34}|x-x_0|^{\alpha}.$ 

Hence, we obtain

$$|T_{\partial U}[f](x) - (T_{\partial U}[f])^+(x_0)| \le M_2 |x - x_0|^{\alpha}, \quad x \in U^+ \cap \Omega, x_0 \in \partial U \cap \Omega,$$

where  $M_2 = J_{31} + J_{32} + J_{33} + J_{34}$ .

In addition, the case when  $6|x_1 - x_2| \ge d$  is similar to the proof of Theorem 3.1.  $\Box$ 

**Theorem 3.4** Let  $U, \partial U, U^+, \Omega$  be stated as above. If  $f \in H^{\alpha}_{\partial U}(0 < \alpha < 1)$  and f is bounded, then for any points  $x_1, x_2 \in U^+ \cap \Omega$ , we have

$$|T_{\partial U}[f](x_1) - (T_{\partial U}[f])^+(x_2)| \le M_3 |x_1 - x_2|^{\alpha},$$

where  $M_3 > 0$  is a constant independent of  $x_1, x_2$ .

**Proof** Let  $|x_1 - x_2| = \delta$ . Because  $\overline{x_1 x_2}$  and  $\partial U \cap \Omega$  are compact, there exist a point  $\tilde{x} \in \overline{x_1 x_2}$  and a point  $\tilde{y_0} \in \partial U \cap \Omega$  such that

$$\widetilde{x} - \widetilde{y_0} = \inf_{x \in \overline{x_1 x_2}, y \in \partial U \cap \Omega} |x - y|$$

Let  $|\widetilde{x} - \widetilde{y_0}| = \delta_0$ . Next we discuss  $|T_{\partial U}[f](x_1) - T_{\partial U}[f](x_2)|$  in three cases.

(1) If  $\delta_0 = 0$ , then  $\tilde{x} = \tilde{y}_0 \in \partial U \cap \Omega$ . Thus from Theorem 3.3, we have

$$\begin{aligned} |T_{\partial U}[f](x_1) - T_{\partial U}[f](x_2)| \\ &\leq |T_{\partial U}[f](x_1) - T_{\partial U}[f](\widetilde{x})| + |T_{\partial U}[f](\widetilde{x}) - T_{\partial U}[f](x_2)| \leq 2M_2 |x_1 - x_2|^{\alpha}. \end{aligned}$$

(2) If  $\delta_0 > 0$  and  $\delta \ge \delta_0$ , then we have

$$|x_1 - \widetilde{y_0}| \le |x_1 - \widetilde{x}| + |\widetilde{x} - \widetilde{y_0}| \le |x_1 - x_2| + |\widetilde{x} - \widetilde{y_0}| = \delta + \delta_0 \le 2\delta.$$

Similarly, we have  $|x_2 - \tilde{y_0}| \le 2\delta$ . Thus, by Theorem 3.3, we get

$$\begin{aligned} |T_{\partial U}[f](x_1) - T_{\partial U}[f](x_2)| &\leq |T_{\partial U}[f](x_1) - T_{\partial U}[f](\widetilde{y_0})| + |T_{\partial U}[f](\widetilde{y_0}) - T_{\partial U}[f](x_2)| \\ &\leq M_2 |x_1 - \widetilde{y_0}|^{\alpha} + M_2 |\widetilde{y_0} - x_2|^{\alpha} \\ &\leq 2^{\alpha + 1} M_2 |x_1 - x_2|^{\alpha}. \end{aligned}$$

(3) If  $\delta_0 > 0$  and  $\delta < \delta_0$ , then by Lemma 2.4, we have

$$|T_{\partial U}[f](x_1) - T_{\partial U}[f](x_2)|$$

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$$\begin{split} &= |T_{\partial U}[f](x_1) - f(\widetilde{y_0}) + f(\widetilde{y_0}) - T_{\partial U}[f](x_2)| \\ &= \Big| \frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x_1) \mathrm{d}\sigma(y) f(y) - \frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x_1) \mathrm{d}\sigma(y) f(\widetilde{y_0}) + \\ &\frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x_2) \mathrm{d}\sigma(y) f(\widetilde{y_0}) - \frac{1}{\omega_{n+1}} \int_{\partial U} l(y, x_2) \mathrm{d}\sigma(y) f(y) \Big| \\ &= \Big| \frac{1}{\omega_{n+1}} \int_{\partial U} [l(y, x_1) - l(y, x_2)] \mathrm{d}\sigma(y) (f(y) - f(\widetilde{y_0})) \Big|. \end{split}$$

Similarly to the theorem 3.1, we construct a sphere  $E_1$  with the center at  $\tilde{y}_0$  and radius  $3\delta$ . Then we construct a sphere  $E_2$  with the center at  $\tilde{y}_0$  and radius R, where R is big enough. The part of  $\partial U$  lying in the interior of  $E_1$  is denoted by  $\partial U_1$ , the part of  $\partial U$  lying between  $E_1$  and  $E_2$  is denoted by  $\partial U_2$ , and the part of  $\partial U$  lying in the exterior  $E_2$  is denoted by  $\partial U_3$ .

In this case, for any  $y \in \partial U$ , we have

$$|y - x_1| \le |y - x_2| + |x_2 - x_1| = |y - x_2| + \delta \le |y - x_2| + \delta_0 \le 2|y - x_2|$$

Similarly, we have  $|y - x_2| \le 2|y - x_1|$ .

Hence, for any  $y \in \partial U$ , we have

$$\frac{1}{2} \le \frac{|y - x_1|}{|y - x_2|} \le 2.$$

In addition, for any  $y \in \partial U$ , we have

$$|y - \tilde{y_0}| \le |y - x_2| + |x_2 - \tilde{x}| + |\tilde{x} - \tilde{y_0}| = |y - x_2| + \delta + \delta_0 \le 3|y - x_2|.$$

Thus, by (3.7),  $f \in H^{\alpha}_{\partial U}$ ,  $|x_1 - x_2| = \delta < \delta_0 \le |y - x_2|$  and the above inequalities, we have

$$\begin{split} \left| \frac{1}{\omega_{n+1}} \int_{\partial U_1} [l(y, x_1) - l(y, x_2)] \mathrm{d}\sigma(y) (f(y) - f(\widetilde{y_0})) \right| \\ &\leq H(f, \partial U, \alpha) \left| \frac{1}{\omega_{n+1}} \int_{\partial U_1} \sum_{k=0}^{n-1} \left| \frac{y - x_1}{y - x_2} \right|^{-(k+1)} |y - x_2|^{-(n+1)} |x_1 - x_2| |y - \widetilde{y_0}|^{\alpha} \mathrm{d}\sigma(y) \\ &\leq J_{35} \left| \frac{1}{\omega_{n+1}} \int_{\partial U_1} |y - x_2|^{-n} |y - \widetilde{y_0}|^{\alpha} \mathrm{d}\sigma(y) \\ &\leq J_{36} \left| \frac{1}{\omega_{n+1}} \int_{\partial U_1} \frac{1}{|y - \widetilde{y_0}|^{n-\alpha}} \mathrm{d}\sigma(y) \\ &\leq J_{37} \left| \frac{1}{\omega_{n+1}} \int_{0}^{3\delta} \frac{1}{\rho_0^{1-\alpha}} \mathrm{d}\rho_0 \\ &= J_{37} \frac{1}{\alpha} 3^{\alpha} \delta^{\alpha} = J_{38} |x_1 - x_2|^{\alpha}. \end{split}$$

And

$$\begin{aligned} &\frac{1}{\omega_{n+1}} \int_{\partial U_2} [l(y,x_1) - l(y,x_2)] \mathrm{d}\sigma(y) (f(y) - f(\widetilde{y_0})) \Big| \\ &\leq H(f,\partial U,\alpha) |\frac{1}{\omega_{n+1}} \int_{\partial U_2} \sum_{k=0}^{n-1} \left| \frac{y - x_1}{y - x_2} \right|^{-(k+1)} |y - x_2|^{-(n+1)} |x_1 - x_2| |y - \widetilde{y_0}|^{\alpha} \mathrm{d}\sigma(y) \\ &\leq J_{38} \Big| \frac{1}{\omega_{n+1}} \int_{\partial U_2} |y - x_2|^{-(n+1)} |y - \widetilde{y_0}|^{\alpha} \mathrm{d}\sigma(y) |x_1 - x_2| \end{aligned}$$

$$\leq J_{39} \left| \frac{1}{\omega_{n+1}} \int_{\partial U_2} \frac{1}{|y - \tilde{y_0}|^{n+1-\alpha}} d\sigma(y) |x_1 - x_2| \right|$$
  
 
$$\leq J_{40} \left| \frac{1}{\omega_{n+1}} \int_{3\delta}^R \frac{1}{\rho_0^{2-\alpha}} d\rho_0 |x_1 - x_2| \right|$$
  
 
$$\leq J_{41} |x_1 - x_2|^{\alpha}.$$

In addition, by the boundedness of f, we have

$$\begin{aligned} \left| \frac{1}{\omega_{n+1}} \int_{\partial U_3} [l(y, x_1) - l(y, x_2)] \mathrm{d}\sigma(y) (f(y) - f(\widetilde{y_0})) \right| \\ &\leq J_{42} \left| \frac{1}{\omega_{n+1}} \int_R^{+\infty} \frac{1}{\rho_0^2} \mathrm{d}\rho_0 |x_1 - x_2| \\ &\leq J_{43} |x_1 - x_2|^{\alpha}. \end{aligned}$$

Therefore, from the above inequality, we obtain

$$|T_{\partial U}[f](x_1) - T_{\partial U}[f](x_2)| \le M_3 |x_1 - x_2|^{\alpha}$$

where  $M_3 = J_{38} + J_{41} + J_{43}$ .  $\Box$ 

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