

## Liouville-Type Theorem for Stable Solutions of the Kirchhoff Equation with Negative Exponent

Yunfeng WEI<sup>1,2,\*</sup>, Caisheng CHEN<sup>2</sup>, Hongwei YANG<sup>3</sup>

1. School of Statistics and Mathematics, Nanjing Audit University, Jiangsu 211815, P. R. China;

2. College of Science, Hohai University, Jiangsu 210098, P. R. China;

3. College of Mathematics and Systems Science, Shandong University of Science and Technology, Shandong 266590, P. R. China

**Abstract** In this paper, we consider the Liouville-type theorem for stable solutions of the following Kirchhoff equation

$$M\left(\int_{\mathbb{R}^N} |\nabla u|^2 dx\right) \Delta u = g(x)u^{-q}, \quad x \in \mathbb{R}^N,$$

where  $M(t) = a + bt^\theta$ ,  $a > 0, b, \theta \geq 0, \theta = 0$  if and only if  $b = 0$ .  $N \geq 2, q > 0$  and the nonnegative function  $g(x) \in L^1_{loc}(\mathbb{R}^N)$ . Under suitable conditions on  $g(x), \theta$  and  $q$ , we investigate the nonexistence of positive stable solution for this problem.

**Keywords** Kirchhoff equation; negative exponent; stable solution; nonexistence

**MR(2010) Subject Classification** 35J60; 35A01; 35B53; 35B35

### 1. Introduction

In this paper, we are concerned with Liouville-type theorem for stable solution of the Kirchhoff equation

$$M\left(\int_{\mathbb{R}^N} |\nabla u|^2 dx\right) \Delta u = g(x)u^{-q}, \quad x \in \mathbb{R}^N, \quad (1.1)$$

where  $M(t) = a + bt^\theta$ ,  $a > 0, b, \theta \geq 0, \theta = 0$  if and only if  $b = 0$ .  $N \geq 2, q > 0, g(x) \in L^1_{loc}(\mathbb{R}^N)$  is nonnegative, the exact assumption on  $g(x)$  will be given latter. Such problem is often referred to as being nonlocal because of the presence of the integral over the entire domain  $\mathbb{R}^N$ . When  $\theta = 1$ , problem (1.1) is analogous to the stationary problem of a model introduced by Kirchhoff [1]. More precisely, Kirchhoff proposed a model given by the equation

$$\rho u_{tt} - \left(\frac{p_0}{h} + \frac{E}{2L} \int_0^L u_x^2 dx\right) u_{xx} = 0, \quad t > 0, \quad x \in (0, L), \quad (1.2)$$

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\* Corresponding author

E-mail address: weiyunfeng@nau.edu.cn (Yunfeng WEI); cshengchen@hhu.edu.cn (Caisheng CHEN); hwyang1979@163.com (Hongwei YANG)

where  $\rho, p_0, h, E, L$  are all positive constants. This equation extends the classical D'Alembert wave equation. For the bounded domain  $\Omega$ , the problem

$$\begin{cases} -(a + b \int_{\Omega} |\nabla u|^2 dx) \Delta u = f(x, u), & x \in \Omega, \\ u(x) = 0, & x \in \partial\Omega \end{cases} \tag{1.3}$$

is related to the stationary analogue of (1.2). Such nonlocal elliptic problem like (1.3) has received a lot of attention and some important and interesting results have been established, see [2–5] and the references therein.

Recently, much attention has been paid for Kirchhoff elliptic equation on  $\mathbb{R}^N$ . Li et al. [6] studied the following problem

$$\left( a + \lambda \int_{\mathbb{R}^N} (|\nabla u|^2 + bu^2) dx \right) (-\Delta u + bu) = f(u), \quad x \in \mathbb{R}^N, \tag{1.4}$$

where  $N \geq 3$  and  $a, b$  are positive constants,  $\lambda \geq 0$  is a parameter. They proved the existence of a positive solution to problem (1.4) with small  $\lambda \in [0, \lambda_0)$ . Fan and Liu [7] studied the existence of multiple solutions for the Kirchhoff equation

$$\left( a + \mu \int_{\mathbb{R}^N} (|\nabla u|^2 + V(x)u^2) dx \right) (-\Delta u + V(x)u) = f(x, u) + g(x)|u|^{q-2}u, \quad x \in \mathbb{R}^N, \tag{1.5}$$

where  $\mu \geq 0$  is small,  $N \geq 3, 1 < q < 2, a > 0$ , and the potential function  $V(x) \in C(\mathbb{R}^N)$  satisfying  $\inf_{x \in \mathbb{R}^N} V(x) > 0$  and  $\text{meas}(\{x \in \mathbb{R}^N | V(x) \leq M\}) < \infty$  for each  $M > 0$ . This assumption guarantees that the embedding  $W^{1,2}(\mathbb{R}^N) \hookrightarrow L^s(\mathbb{R}^N)$  is compact for each  $2 \leq s < 2^*$ . For problem (1.5), the function  $f(x, u)$  verifies  $|f(x, t)| \leq C(1 + |t|^{p-1})$ ,  $\lim_{t \rightarrow 0} t^{-1}f(t) = 0$ ,  $\lim_{t \rightarrow \infty} t^{-1}f(t) = \infty$ , and  $\|g\|_{q'} (q' = 2^*/(2^* - q))$  is small.

Li and Su [8], Nie and Wu [9], also considered problem (1.5), where the potential  $V(x)$  is radially symmetric function. The other class of potential  $V(x) \in C(\mathbb{R}^N)$  satisfying

$$0 < V_0 = \inf_{x \in \mathbb{R}^N} V(x) \leq \lim_{|x| \rightarrow \infty} V(x) = \sup_{x \in \mathbb{R}^N} V(x) := V_{\infty} < \infty \tag{1.6}$$

has also been studied, see [10–12] and the references therein.

We note that, in the above works, one always assumes that the potential function  $V(x) \geq 0$  and  $V(x) \not\equiv 0$  in  $\mathbb{R}^N$ .

On the other hand, the nonexistence and stability of solutions to nonlinear partial differential equations also have been studied in recent years. We refer the readers to [13–21] and the references therein. It is worth pointing out that for the singular elliptic equation (1.1), Ma and Wei in [20] obtained:

**Theorem 1.1** *Let  $q > 0, g(x) = 1$  and  $M(t) = 1$  in (1.1). Moreover, if*

$$2 \leq N < 2 + \frac{4}{1+q}(q + \sqrt{q^2 + q}), \tag{1.7}$$

*then there are no stable positive solutions to (1.1) in  $\mathbb{R}^N$ .*

**Remark 1.2** Obviously, if  $2 < N < 10$ , then (1.7) implies that

$$q > p_0 := -1 - \frac{4(N - 4 + 2\sqrt{N - 1})}{(N - 2)(N - 10)}. \tag{1.8}$$

Motivated by [18, 22, 23], we will study the nonexistence of positive stable solution of (1.1). We now introduce the main results in this paper.

As in [24], let  $X = \mathcal{D}^{1,2}(\mathbb{R}^N)$  be the completion of the space  $C_0^\infty(\mathbb{R}^N)$  endowed with the norm of  $\|u\|_X = (\int_{\mathbb{R}^N} |\nabla u|^2 dx)^{1/2}$ . Then there exists a positive constant  $S$  such that

$$\left(\int_{\mathbb{R}^N} |u|^{2^*} dx\right)^{1/2^*} \leq S \left(\int_{\mathbb{R}^N} |\nabla u|^2 dx\right)^{1/2}, \text{ or } \|u\|_{2^*} \leq S \|u\|_X, \forall u \in X \tag{1.9}$$

which is called the Sobolev’s inequality in [25], where  $2^*$  is the Sobolev critical exponent.

Now we consider the energy functional of (1.1)  $\mathcal{I} : X \rightarrow \mathbb{R}$  defined by

$$\mathcal{I}(u) = \frac{a}{2} \|u\|_X^2 + \frac{b}{2(\theta + 1)} \|u\|_X^{2(\theta+1)} + \frac{1}{1 - q} \int_{\mathbb{R}^N} g(x) u^{1-q} dx. \tag{1.10}$$

It is well known that if  $u \in X$  is a weak solution of (1.1), then for any  $\zeta \in X$ , the function  $E(t) = \mathcal{I}(u + t\zeta)$  satisfies  $E'(0) = 0$ , that is,

$$E'(0) = \mathcal{I}'(u)\zeta = \left(a + b\|u\|_X^{2\theta}\right) \int_{\mathbb{R}^N} \nabla u \cdot \nabla \zeta dx + \int_{\mathbb{R}^N} g(x) u^{-q} \zeta dx = 0, \forall \zeta \in X. \tag{1.11}$$

As in [13], we say that the positive solution  $u$  of (1.1) is stable if  $E''(0) \geq 0$ . A routine calculation shows that

$$\begin{aligned} \frac{E'(t) - E'(0)}{t} &= \frac{\mathcal{I}'(u + t\zeta)\zeta - \mathcal{I}'(u)\zeta}{t} = \frac{b(\|u + t\zeta\|_X^{2\theta} - \|u\|_X^{2\theta})}{t} \int_{\mathbb{R}^N} \nabla u \cdot \nabla \zeta dx + \\ &\quad (a + b\|u + t\zeta\|_X^{2\theta}) \int_{\mathbb{R}^N} |\nabla \zeta|^2 dx + \frac{1}{t} \int_{\mathbb{R}^N} g(x) ((u + t\zeta)^{-q} - u^{-q}) \zeta dx \end{aligned} \tag{1.12}$$

and

$$\begin{aligned} E''(0) &= \lim_{t \rightarrow 0} \frac{E'(t) - E'(0)}{t} = 2b\theta \|u\|_X^{2(\theta-1)} \left(\int_{\mathbb{R}^N} \nabla u \cdot \nabla \zeta dx\right)^2 + \\ &\quad (a + b\|u\|_X^{2\theta}) \int_{\mathbb{R}^N} |\nabla \zeta|^2 dx - q \int_{\mathbb{R}^N} g(x) u^{-q-1} \zeta^2 dx. \end{aligned} \tag{1.13}$$

Set  $Q_u(\zeta) = E''(0)$ . We now define stability as follows.

**Definition 1.3** A positive weak solution  $u \in X$  of (1.1) is stable if  $Q_u(\zeta) \geq 0$  for any  $\zeta \in X$ .

**Remark 1.4** The quadratic form  $Q_u$  is called the second variation of the energy functional  $\mathcal{I}$ . Then, the stability condition translates into the fact that the second variation of the energy functional is non-negative. Thus, all the minima of the functional  $\mathcal{I}$  are stable solutions of (1.1), see [13].

**Remark 1.5** If  $u \in X$  is a stable positive weak solution of (1.1), applying Hölder inequality and (1.13), we deduce that

$$q \int_{\mathbb{R}^N} g(x) u^{-q-1} \zeta^2 dx \leq A \int_{\mathbb{R}^N} |\nabla \zeta|^2 dx, \forall \zeta \in X \tag{1.14}$$

with

$$A = a + b(1 + 2\theta) \|u\|_X^{2\theta}. \tag{1.15}$$

Throughout this paper, we give the following assumption on  $g(x)$ .

(H<sub>1</sub>)  $g(x) \in L^1_{\text{loc}}(\mathbb{R}^N)$  is nonnegative in  $\mathbb{R}^N$ . Moreover, there exist  $k > -2$  and  $R_0, c_0 > 0$  such that  $g(x) \geq c_0|x|^k, \forall |x| \geq R_0$ .

Our main result can be included in the following theorem:

**Theorem 1.6** *Let (H<sub>1</sub>) and  $M(t) = a + bt^\theta, a > 0, b, \theta \geq 0$  hold,  $\theta = 0$  if and only if  $b = 0$ . Assume that one of the following conditions is satisfied:*

- (H<sub>2</sub>)  $\theta \geq 0$  and  $N = 2, q > 0$ ;
- (H<sub>3</sub>)  $0 \leq \theta \leq \frac{3}{2}$  and  $2 < N < 2 + \frac{4(2+k)}{1+2\theta}, q > \alpha_0$ ;
- (H<sub>4</sub>)  $\theta > \frac{3}{2}$  and  $2 < N < 2 + \frac{4(2+k)}{1+2\theta}, q > \beta_0$ ;
- (H<sub>5</sub>)  $\theta > \frac{3}{2}$  and  $N = 2 + \frac{4(2+k)}{1+2\theta}, q > \frac{4}{2\theta-3}$ ;
- (H<sub>6</sub>)  $\theta > \frac{3}{2}$  and  $2 + \frac{4(2+k)}{1+2\theta} < N < 2 + \frac{(1+\sqrt{1+2\theta})(2+k)}{2\theta}, \beta_1 < q < \beta_2$ ,

where

$$\alpha_0 = -1 - \frac{2(2+k)[N-4-k+\sqrt{(N+k)^2-(N-2)^2(1+2\theta)}]}{(N-2)[(N-2)(1+2\theta)-4(2+k)]}. \tag{1.16}$$

$$\beta_0 = -1 - \frac{2(2+k)[N-4-k+\sqrt{(N+k)^2-(N-2)^2(1+2\theta)}]}{(N-2)[(N-2)(1+2\theta)-4(2+k)]}. \tag{1.17}$$

$$\beta_{1,2} = -1 - \frac{2(2+k)[N-4-k \pm \sqrt{(N+k)^2-(N-2)^2(1+2\theta)}]}{(N-2)[(N-2)(1+2\theta)-4(2+k)]}. \tag{1.18}$$

Then (1.1) has no positive weak stable solution.

**Remark 1.7** (i) If  $\theta = 0$ , we obtain

$$\alpha_0 = -1 - \frac{2(2+k)[N-4-k+\sqrt{(2N-2+k)(2+k)}]}{(N-2)(N-10-4k)}. \tag{1.19}$$

Then  $\alpha_0$  is equal to the exponent  $p(N, \alpha)$  in [26].

(ii) If  $\theta = 0, k = 0$ , we obtain

$$\alpha_0 = -1 - \frac{4(N-4+2\sqrt{N-1})}{(N-2)(N-10)}. \tag{1.20}$$

Then  $\alpha_0$  is equal to the exponent  $q_c(2, N)$  in [27] and  $\alpha_0 = p_0$ , where  $p_0$  is the critical exponent (1.8) and coincides with that in [20].

## 2. Proof of Theorem 1.6

To prove the nonexistence of positive weak stable solution of (1.1), we use the test function method, which has been used in [18, 22, 23]. Since Kirchhoff equation (1.1) is nonlocal, some modification in choosing test functions is necessary.

We first establish the following lemma.

**Lemma 2.1** *Let  $u \in C^{1,\omega}_{\text{loc}}(\mathbb{R}^N)$  ( $0 < \omega < 1$ ) be a positive weak stable solution of (1.1) with  $q > 0$ . Then for every  $\gamma \in (\gamma(q), -1)$ , where*

$$\gamma(t) = -\frac{1+2\theta+2t+2\sqrt{t(t+1+2\theta)}}{1+2\theta}, \quad t > 0 \tag{2.1}$$

and for any constant  $m \geq \frac{q-\gamma}{q+1}$ , there exists a positive constant  $C$  depending on  $q, \gamma, m, a, b, \theta$  such that

$$\int_{\mathbb{R}^N} (g(x)u^{\gamma-q} + |\nabla u|^2 u^{\gamma-1}) \varphi^{2m} dx \leq CA^{\frac{q-\gamma}{q+1}} \int_{\mathbb{R}^N} g(x)^{\frac{\gamma+1}{q+1}} |\nabla \varphi|^{\frac{2(q-\gamma)}{q+1}} dx, \tag{2.2}$$

where  $\varphi(x) \in C_0^1(\mathbb{R}^N)$  is any nonnegative function with  $0 \leq \varphi(x) \leq 1$  and  $A$  is given by (1.15).

**Proof** Let  $u \in C_{loc}^{1,\omega}(\mathbb{R}^N)$  ( $0 < \omega < 1$ ) be a positive weak stable solution of (1.1) and  $\gamma < -1$ . Choosing  $\zeta = u^\gamma \varphi^2$  as a test function in (1.11), we obtain

$$|\gamma|A_1 \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx \leq 2A_1 \int_{\mathbb{R}^N} |\nabla u| |\nabla \varphi| u^\gamma \varphi dx + \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx, \tag{2.3}$$

where  $A_1 = a + b\|u\|_X^{2\theta}$ . Applying Young's inequality with any  $\varepsilon \in (0, 1)$ , we get

$$2 \int_{\mathbb{R}^N} |\nabla u| |\nabla \varphi| u^\gamma \varphi dx \leq \varepsilon \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx + C_1 \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx. \tag{2.4}$$

Here and in what follows, we denote by  $C_j$  a positive constant depending on  $\varepsilon$  and  $q, \gamma, \theta$ . Combining (2.3) with (2.4) enables us to deduce

$$(|\gamma| - \varepsilon)A_1 \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx \leq \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx + C_1 A_1 \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx. \tag{2.5}$$

On the other hand, using the stability assumption with  $\zeta = u^{\frac{\gamma+1}{2}} \varphi$  in (1.14) yields

$$q \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx \leq \frac{(1+\gamma)^2}{4} A \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx + A \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx + (1+|\gamma|)A \int_{\mathbb{R}^N} |\nabla u| |\nabla \varphi| u^\gamma \varphi dx. \tag{2.6}$$

By Young's inequality, it follows that

$$(1+|\gamma|) \int_{\mathbb{R}^N} |\nabla u| |\nabla \varphi| u^\gamma \varphi dx \leq \varepsilon \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx + C_2 \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx, \tag{2.7}$$

where  $\varepsilon$  coincides with that in (2.4). Plugging (2.7) into (2.6), we can deduce

$$q \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx \leq \frac{[(1+\gamma)^2 + 4\varepsilon]}{4} A \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx + C_3 A \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx. \tag{2.8}$$

Furthermore, from (2.5) and (2.8) we have

$$q \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx \leq \frac{[(1+\gamma)^2 + 4\varepsilon]A}{4(|\gamma| - \varepsilon)A_1} \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx + C_4 A \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx \leq \frac{[(1+\gamma)^2 + 4\varepsilon](1+2\theta)}{4(|\gamma| - \varepsilon)} \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx + C_4 A \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx, \tag{2.9}$$

that is

$$q_\varepsilon \int_{\mathbb{R}^N} g(x)u^{\gamma-q} \varphi^2 dx \leq C_4 A \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx, \tag{2.10}$$

with

$$q_\varepsilon = q - \frac{[(1+\gamma)^2 + 4\varepsilon](1+2\theta)}{4(|\gamma| - \varepsilon)}, \quad \lim_{\varepsilon \rightarrow 0^+} q_\varepsilon = q_0 = q - \frac{(1+\gamma)^2(1+2\theta)}{4|\gamma|}. \tag{2.11}$$

Thanks to  $\gamma \in (\gamma(q), -1)$ ,  $q_0 > 0$  holds, where  $\gamma(t)$  is defined by (2.1). Thus, we can select sufficiently small  $\varepsilon > 0$  such that  $q_\varepsilon > 0$ .

Applying (2.10) and (2.5), we conclude that

$$\int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^2 dx \leq C_5 \int_{\mathbb{R}^N} |\nabla \varphi|^2 u^{\gamma+1} dx. \tag{2.12}$$

Now we claim that (2.2) is true. In fact, we can choose some constant  $m$  large enough satisfying

$$\frac{(m-1)(\gamma-q)}{\gamma+1} \geq m, \text{ or } m \geq \frac{q-\gamma}{q+1}. \tag{2.13}$$

By virtue of  $0 \leq \varphi(x) \leq 1$  in  $\mathbb{R}^N$ , one can achieve

$$[\varphi(x)]^{\frac{2(m-1)(\gamma-q)}{\gamma+1}} \leq [\varphi(x)]^{2m}, \quad \forall x \in \mathbb{R}^N. \tag{2.14}$$

Replacing  $\varphi$  in (2.10) with  $\varphi^m$  and utilizing the Hölder inequality, we arrive at

$$\begin{aligned} \int_{\mathbb{R}^N} g(x) u^{\gamma-q} \varphi^{2m} dx &\leq C_6 A \int_{\mathbb{R}^N} |\nabla \varphi|^2 \varphi^{2(m-1)} u^{\gamma+1} dx \\ &\leq C_6 A \left( \int_{\mathbb{R}^N} g(x) u^{\gamma-q} \varphi^{\frac{2(m-1)(\gamma-q)}{\gamma+1}} dx \right)^{\frac{\gamma+1}{\gamma-q}} \left( \int_{\mathbb{R}^N} g(x)^{\frac{\gamma+1}{q+1}} |\nabla \varphi|^{\frac{2(q-\gamma)}{q+1}} dx \right)^{\frac{q+1}{q-\gamma}} \\ &\leq C_6 A \left( \int_{\mathbb{R}^N} g(x) u^{\gamma-q} \varphi^{2m} dx \right)^{\frac{\gamma+1}{\gamma-q}} \left( \int_{\mathbb{R}^N} g(x)^{\frac{\gamma+1}{q+1}} |\nabla \varphi|^{\frac{2(q-\gamma)}{q+1}} dx \right)^{\frac{q+1}{q-\gamma}}. \end{aligned} \tag{2.15}$$

Consequently, we obtain

$$\int_{\mathbb{R}^N} g(x) u^{\gamma-q} \varphi^{2m} dx \leq C_7 A^{\frac{q-\gamma}{q+1}} \int_{\mathbb{R}^N} g(x)^{\frac{\gamma+1}{q+1}} |\nabla \varphi|^{\frac{2(q-\gamma)}{q+1}} dx. \tag{2.16}$$

Analogously, with  $\varphi$  replaced by  $\varphi^m$  in (2.12), it follows from (2.12), (2.15) and (2.16) that

$$\begin{aligned} \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^{2m} dx &\leq C_8 \int_{\mathbb{R}^N} |\nabla \varphi|^2 \varphi^{2(m-1)} u^{\gamma+1} dx \\ &\leq C_9 A^{\frac{q-\gamma}{q+1}} \int_{\mathbb{R}^N} g(x)^{\frac{\gamma+1}{q+1}} |\nabla \varphi|^{\frac{2(q-\gamma)}{q+1}} dx. \end{aligned} \tag{2.17}$$

Combining (2.16) with (2.17) enables us to deduce (2.2). The proof is completed.  $\square$

**Proof of Theorem 1.6** Define  $\varphi_0(s) \in C_0^1[0, +\infty)$  with

$$\varphi_0(s) = \begin{cases} 1, & 0 \leq s \leq 1, \\ 0, & s > 2. \end{cases} \tag{2.18}$$

Let  $\varphi(x) = \varphi_0(\frac{|x|}{R})$  for  $R \geq R_0$ , where  $R_0$  is given in  $(H_1)$ . Obviously,  $\varphi(x) \in C_0^1(\mathbb{R}^N)$  with  $0 \leq \varphi(x) \leq 1$ . A direct calculation shows that there exists  $C > 0$  such that  $|\nabla \varphi(x)| \leq CR^{-1}$ ,  $x \in \overline{B}_{2R} \setminus \overline{B}_R$  and  $|\nabla \varphi(x)| = 0$ ,  $x \in \overline{B}_R \cup \overline{B}_{2R}^c$ , where  $B_r = \{x \in \mathbb{R}^N : |x| < r\}$ .

Suppose on the contrary that (1.1) admits a positive weak stable solution, then utilizing the assumption  $(H_1)$  and the estimate (2.2), we have

$$\begin{aligned} \int_{\mathbb{R}^N} g(x) u^{\gamma-q} \varphi^{2m} dx + \int_{\mathbb{R}^N} |\nabla u|^2 u^{\gamma-1} \varphi^{2m} dx \\ \leq C A^{\frac{q-\gamma}{q+1}} R^{-\frac{2(q-\gamma)}{q+1}} \int_{R < |x| \leq 2R} |x|^{\frac{k(\gamma+1)}{q+1}} dx \end{aligned}$$

$$\leq CA^{\frac{q-\gamma}{q+1}} R^{N-\frac{2(q-\gamma)-k(\gamma+1)}{q+1}}, \tag{2.19}$$

where  $C$  denote various positive constants.

Set

$$\rho = N - \frac{2(q-\gamma) - k(\gamma+1)}{q+1}. \tag{2.20}$$

Obviously, if  $\rho < 0$ , passing to the limits as  $R \rightarrow +\infty$  in (2.19), we deduce a contradiction. Next, we are devoted to choosing some appropriate  $\gamma$  such that  $\rho < 0$ . To do this, we define the function

$$h(t) = \frac{2[t - \gamma(t)] - k[\gamma(t) + 1]}{t + 1}, \quad t > 0, \tag{2.21}$$

where  $\gamma(t)$  is given by (2.1). A direct calculation leads to

$$\lim_{t \rightarrow 0^+} \gamma(t) = -1, \quad \gamma'(t) < 0, \quad t > 0, \quad \lim_{t \rightarrow +\infty} \gamma(t) = -\infty, \tag{2.22}$$

and

$$\lim_{t \rightarrow 0^+} h(t) = 2 \leq N, \quad \lim_{t \rightarrow +\infty} h(t) = 2 + \frac{4(2+k)}{1+2\theta}, \tag{2.23}$$

$$h'(t) = \frac{(2+k)(2\sqrt{t(t+1+2\theta)} + 1 + 2\theta + t(1-2\theta))}{(1+2\theta)\sqrt{t(t+1+2\theta)}(t+1)^2}, \quad t > 0. \tag{2.24}$$

A routine calculation shows that if  $0 \leq \theta \leq \frac{3}{2}$ , then  $h(t)$  is strictly increasing on  $(0, +\infty)$ ; if  $\theta > \frac{3}{2}$ , then  $h(t)$  is strictly increasing on  $(0, \frac{1+2\theta+2\sqrt{1+2\theta}}{2\theta-3})$  and strictly decreasing on  $(\frac{1+2\theta+2\sqrt{1+2\theta}}{2\theta-3}, +\infty)$ . Moreover,  $h(\frac{1+2\theta+2\sqrt{1+2\theta}}{2\theta-3}) = 2 + \frac{(1+\sqrt{1+2\theta})(2+k)}{2\theta}$ ,  $h(\frac{4}{2\theta-3}) = 2 + \frac{4(2+k)}{1+2\theta}$ .

Therefore, if  $N = 2$  and  $\theta \geq 0$ , then  $N < h(t), \forall t > 0$ . So if we fix  $\gamma \in (\gamma(t), -1)$  suitably near  $\gamma(t)$ , we obtain

$$N < \frac{2(t-\gamma) - k(\gamma+1)}{t+1}. \tag{2.25}$$

Letting  $R \rightarrow +\infty$  in (2.19), we get a contradiction.

If  $2 < N < 2 + \frac{4(2+k)}{1+2\theta}$  and  $0 \leq \theta \leq \frac{3}{2}$ , by the properties of the function  $h(t)$ , there exists a unique  $\alpha_0 > 0$  such that  $N < h(t), t > \alpha_0$ . From this, taking  $R \rightarrow +\infty$  in (2.19), we deduce a contradiction. Clearly,  $\alpha_0$  may be deduced from the equation  $N = h(q)$ , which is given in (1.16).

If  $2 < N < 2 + \frac{4(2+k)}{1+2\theta}$  and  $\theta > \frac{3}{2}$ , by the properties of the function  $h(t)$ , there exists a unique  $\beta_0 > 0$  such that  $N < h(t), t > \beta_0$ . From this, letting  $R \rightarrow +\infty$  in (2.19), we get a contradiction. Clearly,  $\beta_0$  may be deduced from the equation  $N = h(q)$ , which is given in (1.17).

If  $N = 2 + \frac{4(2+k)}{1+2\theta}$  and  $\theta > \frac{3}{2}$ , note that  $h(t) > h(\frac{4}{2\theta-3}) = 2 + \frac{4(2+k)}{1+2\theta}, t > \frac{4}{2\theta-3}$ , we have  $N < h(t), t > \frac{4}{2\theta-3}$ . From this, letting  $R \rightarrow +\infty$  in (2.19), we get a contradiction.

Assume now  $2 + \frac{4(2+k)}{1+2\theta} < N < 2 + \frac{(1+\sqrt{1+2\theta})(2+k)}{2\theta}$  and  $\theta > \frac{3}{2}$ , by the properties of the function  $h(t)$ , there exist  $\beta_{1,2} > \frac{4}{2\theta-3}$  such that  $N < h(t)$  for  $\beta_1 < t < \beta_2$ . From this, letting  $R \rightarrow +\infty$  in (2.19), we get a contradiction. Clearly,  $\beta_{1,2}$  may be deduced from the equation  $N = h(q)$ , which is given in (1.18). The proof of Theorem 1.6 is completed.  $\square$

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