

# Oscillation of High Order Neutral Delay Difference Equations with Continuous Arguments

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**Abstract** In this paper, we study oscillation of solutions for a class of high order neutral delay difference equations with variable coefficients

$$\Delta_{\tau}^m [x(t) - c(t)x(t - \tau)] = (-1)^m p(t)x(t - \sigma), \quad t \geq t_0 > 0.$$

Some sufficient conditions are obtained for bounded oscillation of the solutions.

**Keywords** delay difference equation; bounded solution; oscillation; nonoscillation.

**Document code** A

**MR(2000) Subject Classification** 34C10

**Chinese Library Classification** O175.2

## 1. Introduction

Recently, a lot of literature focus on the oscillatory theory for delay difference equations, and there have been some results on the second order neutral difference equations [1–8]. However, there are relatively scarce papers related to oscillation for second order neutral difference equations with continuous arguments and even order neutral delay difference equations with continuous arguments [9, 10].

Consider the following  $m$ -order neutral delay difference equation with variable coefficients

$$\Delta_{\tau}^m [x(t) - c(t)x(t - \tau)] = (-1)^m p(t)x(t - \sigma), \quad t \geq t_0 > 0, \quad (1)$$

where (H):  $\tau, t_0$  are fixed real numbers with  $\tau \geq 0, t_0 \geq 0, m$  is a positive integer,  $\sigma = k\tau$  and  $k$  is some positive integer,  $p(t) \in C([t_0, +\infty), R^+)$ ,  $p(t) \not\equiv 0, \Delta_{\tau}x(t) = x(t + \tau) - x(t), \Delta_{\tau}^2x(t) = \Delta_{\tau}(\Delta_{\tau}x(t))$ .

By a solution of (1) we mean a continuous function  $x(t)$  which is defined for  $-\rho \leq t \leq 0$ , where  $\rho = \max\{\tau, \sigma\}$ , and satisfies Eq.(1) for  $t \geq t_0$ . Clearly, if

$$x(t) = \Phi(t), \quad -\rho \leq t \leq 0 \quad (2)$$

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Received August 15, 2007; Accepted February 26, 2008

Supported by the National Natural Science Foundation of China (Grant No.10571050) and the Science and Research Fund for Higher College of Hunan Province (Grant No.06C054).

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are given, where  $\Phi(t) \in C([-\rho, 0], R)$ , and  $c(t)$ ,  $p(t)$  of (1) are continuous functions, then Eq.(1) has a unique solution satisfying the initial conditions (2).

As is customary, a solution  $x(t)$  of (1) is said to be eventually positive if  $x(t) > 0$  for all large  $t$ , and eventually negative if  $x(t) < 0$  for all large  $t$ . A solution  $x(t)$  of (1) is said to be oscillatory if it is neither eventually positive nor eventually negative.

## 2. Lemma

In this paper, we will establish the bounded oscillation criteria for Eq.(1). To prove our results, we need the following Lemma.

**Lemma 2.1** *Assume that there exists a constant  $\alpha$  ( $0 \leq \alpha < 1$ ) such that  $\alpha \leq c(t) < 1$ . If  $x(t)$  is an eventually positive bounded solution of (1), set  $y(t) = x(t) - c(t)x(t - \tau)$ , then we have eventually  $(-1)^m \Delta_\tau^m y(t) \geq 0$ ,  $(-1)^m \Delta_\tau^{m-1} y(t) < 0$ ,  $(-1)^m \Delta_\tau^{m-2} y(t) > 0, \dots, \Delta_\tau y(t) < 0, y(t) > 0$ .*

**Proof** Assume that  $x(t)$  is an eventually positive bounded solution of Eq.(1) such that

$$x(t) > 0, x(t - \tau) > 0, x(t - \sigma) > 0, \quad t \geq t_1 \geq t_0.$$

Set

$$y(t) = x(t) - c(t)x(t - \tau), \quad (3)$$

then

$$(-1)^m \Delta_\tau^m y(t) = (-1)^{2m} p(t)x(t - \sigma) \geq 0,$$

that is

$$(-1)^m \Delta_\tau^{m-1} y(t + \tau) \geq (-1)^m \Delta_\tau^{m-1} y(t), \quad t \geq t_1. \quad (4)$$

From (H), we have  $\Delta_\tau^m y(t) \neq 0$ , which means that either eventually  $(-1)^m \Delta_\tau^{m-1} y(t) > 0$  or eventually  $(-1)^m \Delta_\tau^{m-1} y(t) < 0$ . Furthermore, we have  $(-1)^m \Delta_\tau^{m-2} y(t), \dots, \Delta_\tau y(t)$  are either eventually positive or eventually negative. If  $(-1)^m \Delta_\tau^{m-1} y(t) > 0$ , then there exists  $\tilde{t}_0 \geq t_1$  such that  $(-1)^m \Delta_\tau^{m-1} y(\tilde{t}_0) > 0$ . Thus owing to (4), we have

$$(-1)^m \Delta_\tau^{m-1} y(\tilde{t}_0 + i\tau) \geq (-1)^m \Delta_\tau^{m-1} y(\tilde{t}_0), \quad i \geq 1.$$

Summing up the above inequality from  $i = 1$  to  $i = n$ , where  $n$  is a positive integer, we get

$$(-1)^m \Delta_\tau^{m-2} y[\tilde{t}_0 + (n+1)\tau] - (-1)^m \Delta_\tau^{m-2} y(\tilde{t}_0 + \tau) \geq n \cdot (-1)^m \Delta_\tau^{m-1} y(\tilde{t}_0).$$

Hence

$$\lim_{n \rightarrow \infty} (-1)^m \Delta_\tau^{m-2} y[\tilde{t}_0 + (n+1)\tau] = +\infty,$$

which contradicts the fact that  $x(t)$  is eventually bounded, and so  $(-1)^m \Delta_\tau^{m-1} y(t) < 0$  eventually holds. By the same argument as in the above proof, we have eventually  $(-1)^m \Delta_\tau^{m-2} y(t) > 0, \dots, \Delta_\tau y(t) < 0$ . It follows that  $y(t) > 0$  eventually holds. Otherwise, eventually  $y(t) < 0$ , then there must exist constants  $\tilde{t}_1 \geq t_1$  and  $\mu > 0$  such that

$$y(\tilde{t}_1) \leq -\mu.$$

Thus

$$y(\tilde{t}_1 + i\tau) \leq -\mu, \quad i = 1, 2, \dots$$

From (3) and the fact that  $\alpha \leq c(t) < 1$ , we have

$$x(\tilde{t}_1 + i\tau) < x[\tilde{t}_1 + (i-1)\tau] - \mu, \quad i = 1, 2, \dots$$

Summing up the above inequality from  $i = 1$  to  $i = n$ , we obtain

$$x(\tilde{t}_1 + n\tau) < x(\tilde{t}_1) - n \cdot \mu.$$

Therefore

$$\lim_{n \rightarrow \infty} x(\tilde{t}_1 + n\tau) = -\infty,$$

which contradicts the fact that  $x(t)$  is an eventually positive bounded solution, so eventually  $y(t) > 0$ . The proof is thus completed.  $\square$

### 3. Results and Proofs

**Theorem 3.1** Assume that (H) holds and there exists a constant  $\alpha$  ( $0 \leq \alpha < 1$ ) such that  $\alpha \leq c(t) < 1$ . For  $t \geq t_0$ ,  $k > 1$ , if

$$\limsup_{n \rightarrow \infty} \sum_{i=n-k}^n C_{i-(n-k)+m-1}^{m-1} p(t+i\tau) > 1 - \alpha, \quad (5)$$

then every bounded solution of Eq.(1) oscillates.

**Proof** Assume for the sake of contradiction that Eq.(1) has an eventually positive bounded solution  $x(t)$  such that

$$x(t - \tau) > 0, \quad x(t - \sigma) > 0, \quad t \geq t_1 \geq t_0.$$

Set

$$y(t) = x(t) - c(t)x(t - \tau). \quad (6)$$

Then by Lemma, there exists  $t_2 \geq t_1$  such that

$$(-1)^m \Delta_\tau^m y(t) \geq 0, \quad (-1)^m \Delta_\tau^{m-1} y(t) < 0, \dots, \Delta_\tau y(t) < 0, \quad y(t) > 0, \quad t \geq t_2.$$

Let  $h(t) = [\frac{t-t_2}{\tau}]$ , where  $[\cdot]$  denotes the greatest integer function. Then we have

$$\begin{aligned} x(t) &= y(t) + c(t)x(t - \tau) \geq y(t) + \alpha x(t - \tau) \\ &= y(t) + \alpha[y(t - \tau) + c(t - \tau)x(t - 2\tau)] \\ &\geq y(t) + \alpha y(t - \tau) + \alpha^2 x(t - 2\tau) \\ &\geq y(t) + \alpha y(t - \tau) + \alpha^2 y(t - 2\tau) + \dots + \alpha^{h(t)-1} y[t - (h(t) - 1)\tau] + \\ &\quad \alpha^{h(t)} x(t - h(t)\tau), \quad t \geq t_2 + \tau. \end{aligned}$$

From the fact that  $\Delta_\tau y(t) < 0$ , we get

$$x(t) \geq (1 + \alpha + \alpha^2 + \dots + \alpha^{h(t)-1})y(t) = \frac{1 - \alpha^{h(t)}}{1 - \alpha} y(t), \quad t \geq t_2 + \tau. \quad (7)$$

By means of (5), we know there exists a sufficiently small positive number  $\varepsilon$  ( $0 < \varepsilon < 1$ ) such that

$$\limsup_{n \rightarrow \infty} \sum_{i=n-k}^n C_{i-(n-k)+m-1}^{m-1} p(t+i\tau) > \frac{1-\alpha}{1-\varepsilon}. \quad (8)$$

For this  $\varepsilon$ , since  $h(t) \rightarrow \infty$  ( $t \rightarrow \infty$ ),  $0 \leq \alpha < 1$ , there must exist  $t_3 \geq t_2 + \tau$  such that

$$\frac{1-\alpha^{h(t)}}{1-\alpha} \geq \frac{1-\varepsilon}{1-\alpha}, \quad t \geq t_3.$$

By (7), we get

$$x(t) \geq \frac{1-\alpha^{h(t)}}{1-\alpha} y(t) \geq \frac{1-\varepsilon}{1-\alpha} y(t), \quad t \geq t_3. \quad (9)$$

For sufficiently large  $t_4 > t_3$ , let  $t = t_4 + i\tau$ , where  $i$  is a positive integer. From (7) and the fact that  $\sigma = k\tau$ , we obtain

$$\Delta_\tau^m y(t_4 + i\tau) = (-1)^m p(t_4 + i\tau) x(t_4 + i\tau - k\tau),$$

that is

$$\Delta_\tau^{m-1} y[t_4 + (i+1)\tau] - \Delta_\tau^{m-1} y(t_4 + i\tau) = (-1)^m p(t_4 + i\tau) x[t_4 + (i-k)\tau].$$

Summing up the last inequality from  $i < n$  to  $n$ , we get

$$\Delta_\tau^{m-1} y[t_4 + (n+1)\tau] - \Delta_\tau^{m-1} y(t_4 + i\tau) = (-1)^m \sum_{j=i}^n p(t_4 + j\tau) x[t_4 + (j-k)\tau].$$

In view of the Lemma 2.1, it follows that

$$(-1)^m \Delta_\tau^{m-1} y(t_4 + i\tau) \leq - \sum_{j=i}^n p(t_4 + j\tau) x[t_4 + (j-k)\tau]. \quad (10)$$

Hence, summing up (10) from  $i = n-k$  to  $i = n$ , we have

$$-(-1)^m \Delta_\tau^{m-2} y[t_4 + (n-k)\tau] \leq - \sum_{i=n-k}^n \sum_{j=i}^n p(t_4 + j\tau) x[t_4 + (j-k)\tau].$$

By repeating the same procedure  $(m-1)$  times, we obtain

$$y[t_4 + (n+1)\tau] - y[t_4 + (n-k)\tau] \leq - \sum_{v=n-k}^n \sum_{r=v}^n \cdots \sum_{i=t}^n \sum_{j=i}^n p(t_4 + j\tau) x[t_4 + (j-k)\tau].$$

Consequently, we get

$$\begin{aligned} y[t_4 + (n+1)\tau] - y[t_4 + (n-k)\tau] &\leq - \sum_{i=n-k}^n C_{i-(n-k)+m-1}^{m-1} p(t_4 + i\tau) x[t_4 + (i-k)\tau] \\ &\leq - \sum_{i=n-k}^n C_{i-(n-k)+m-1}^{m-1} p(t_4 + i\tau) \frac{1-\varepsilon}{1-\alpha} y[t_4 + (i-k)\tau] \\ &\leq - \frac{1-\varepsilon}{1-\alpha} y[t_4 + (n-k)\tau] \sum_{i=n-k}^n C_{i-(n-k)+m-1}^{m-1} p(t_4 + i\tau). \end{aligned}$$

Thus

$$y[t_4 + (n + 1)\tau] + y[t_4 + (n - k)\tau] \left[ \frac{1 - \varepsilon}{1 - \alpha} \sum_{i=n-k}^n C_{i-(n-k)+m-1}^{m-1} p(t_4 + i\tau) - 1 \right] \leq 0,$$

which contradicts (8). The proof is completed.  $\square$

**Theorem 3.2** Assume that (H) holds and there exists a constant  $\alpha$  such that  $\alpha \leq c(t) < 0$ . Set  $k > 1$ . If

$$\limsup_{t \rightarrow \infty} \left[ -c(t - \sigma) \frac{p(t)}{p(t - \tau)} \right] = \beta \in (0, +\infty), \tag{11}$$

and for  $t \geq t_0$ ,

$$\limsup_{n \rightarrow \infty} \sum_{i=n+1-k}^n C_{i-(n+1-k)+m-1}^{m-1} p(t + i\tau) > 1 + \beta, \tag{12}$$

then every bounded solution of Eq.(1) oscillates.

**Proof** For the sake of contradiction, assume that Eq.(1) has an eventually positive bounded solution  $x(t)$ . Set  $y(t) = x(t) - c(t)x(t - \tau)$ . By Lemma 2.1, there exists  $t_1 \geq t_0$  such that

$$(-1)^m \Delta_\tau^m y(t) \geq 0, (-1)^m \Delta_\tau^{m-1} y(t) < 0, \dots, \Delta_\tau y(t) < 0, y(t) > 0, \quad t \geq t_1.$$

By means of (12), there must exist a constant  $\mu > 1$  such that

$$\limsup_{n \rightarrow \infty} \sum_{i=n+1-k}^n C_{i-(n+1-k)+m-1}^{m-1} p(t + i\tau) > 1 + \mu\beta. \tag{13}$$

For this  $\mu$ , it follows from (11) that there must exist  $t_2 \geq t_1$  such that

$$-c(t - \sigma) \frac{p(t)}{p(t - \tau)} \leq \mu\beta, \quad t \geq t_2. \tag{14}$$

In view of (1), we get

$$\begin{aligned} & \Delta_\tau^m y(t) - c(t - \sigma) \frac{p(t)}{p(t - \tau)} \Delta_\tau^m y(t - \tau) \\ &= (-1)^m p(t)x(t - \sigma) - c(t - \sigma) \frac{p(t)}{p(t - \tau)} (-1)^m p(t - \tau)x(t - \tau - \sigma) \\ &= (-1)^m p(t)[x(t - \sigma) - c(t - \sigma)x(t - \tau - \sigma)] \\ &= (-1)^m p(t)y(t - \sigma), \quad t \geq t_2. \end{aligned}$$

From (14), we have  $(-1)^m [\Delta_\tau^m y(t) + \mu\beta \Delta_\tau^m y(t - \tau)] \geq p(t)y(t - \sigma), t \geq t_2$ .

Set  $z(t) = y(t) + \mu\beta y(t - \tau)$ . Then

$$(-1)^m \Delta_\tau^m z(t) \geq p(t)y(t - \sigma), \quad t \geq t_2. \tag{15}$$

It is easy to see that

$$(-1)^m \Delta_\tau^m z(t) \geq 0, (-1)^m \Delta_\tau^{m-1} z(t) < 0, \dots, \Delta_\tau z(t) < 0, z(t) > 0, \quad t \geq t_2.$$

On the other hand, on account of  $\Delta_\tau y(t) < 0$ , we have

$$z(t) = y(t) + \mu\beta y(t - \tau) \leq (1 + \mu\beta)y(t - \tau), \quad t \geq t_2.$$

That is

$$y(t) \geq \frac{1}{1 + \mu\beta} z(t + \tau), \quad t \geq t_2 + \tau = t_3.$$

Substituting the above inequality into (15) yields

$$(-1)^m \Delta_\tau^m z(t) \geq p(t) \frac{1}{1 + \mu\beta} z(t - \sigma + \tau), \quad t \geq t_3 + \sigma. \quad (16)$$

Take a sufficiently large number  $t_4 > t_3 + \sigma$  and set  $t = t_4 + i\tau$ , where  $i$  is a positive integer. Then from the fact that  $\sigma = k\tau$ , we get

$$(-1)^m \Delta_\tau^m z(t_4 + i\tau) \geq \frac{1}{1 + \mu\beta} p(t_4 + i\tau) z[t_4 + (i + 1 - k)\tau].$$

Summing up the last inequality from  $i$  to  $n$  ( $n \geq i$ ), we have

$$(-1)^m \Delta_\tau^{m-1} z[t_4 + (n + 1)\tau] - (-1)^m \Delta_\tau^{m-1} z(t_4 + i\tau) \geq \frac{1}{1 + \mu\beta} \sum_{j=i}^n p(t_4 + j\tau) z[t_4 + (j + 1 - k)\tau].$$

Since  $(-1)^m \Delta_\tau^{m-1} z[t_4 + (n + 1)\tau] < 0$ , we obtain

$$-(-1)^m \Delta_\tau^{m-1} z(t_4 + i\tau) \geq \frac{1}{1 + \mu\beta} \sum_{j=i}^n p(t_4 + j\tau) z[t_4 + (j + 1 - k)\tau].$$

Summing up the above inequality from  $i = n + 1 - k$  to  $i = n$ , we have

$$\begin{aligned} & -(-1)^m \Delta_\tau^{m-2} z[t_4 + (n + 1)\tau] + (-1)^m \Delta_\tau^{m-2} z[t_4 + (n + 1 - k)\tau] \\ & \geq \frac{1}{1 + \mu\beta} \sum_{i=n+1-k}^n \sum_{j=i}^n p(t_4 + j\tau) z[t_4 + (j + 1 - k)\tau]. \end{aligned}$$

Since  $(-1)^m \Delta_\tau^{m-2} z[t_4 + (n + 1)\tau] > 0$ , we get

$$(-1)^m \Delta_\tau^{m-2} z[t_4 + (n + 1 - k)\tau] \geq \frac{1}{1 + \mu\beta} \sum_{i=n+1-k}^n \sum_{j=i}^n p(t_4 + j\tau) z[t_4 + (j + 1 - k)\tau].$$

Repeating the same procedure ( $m - 1$ ) times gives

$$\begin{aligned} & z[t_4 + (n + 1 - k)\tau] - z[t_4 + (n + 1)\tau] \\ & \geq \frac{1}{1 + \mu\beta} \sum_{v=n+1-k}^n \sum_{r=v}^n \cdots \sum_{i=r}^n \sum_{j=i}^n p(t_4 + j\tau) z[t_4 + (j + 1 - k)\tau] \\ & = \frac{1}{1 + \mu\beta} \sum_{i=n+1-k}^n C_{i-(n+1-k)+m-1}^{m-1} p(t_4 + i\tau) z[t_4 + (i + 1 - k)\tau]. \end{aligned}$$

From the fact that  $\Delta_\tau z(t) < 0$ , we have

$$\begin{aligned} & z[t_4 + (n + 1 - k)\tau] - z[t_4 + (n + 1)\tau] \\ & \geq \frac{1}{1 + \mu\beta} z[t_4 + (n + 1 - k)\tau] \sum_{i=n+1-k}^n C_{i-(n+1-k)+m-1}^{m-1} p(t_4 + i\tau). \end{aligned}$$

Thus

$$z[t_4 + (n + 1)\tau] + z[t_4 + (n + 1 - k)\tau] \left[ \frac{1}{1 + \mu\beta} \sum_{i=n+1-k}^n C_{i-(n+1-k)+m-1}^{m-1} p(t_4 + i\tau) - 1 \right] \leq 0,$$

which contradicts (13). The proof is completed.  $\square$

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